



EECS 483: Compiler Construction

Lecture 18: Optimization and Dataflow Analysis

**March 23
Winter Semester 2025**

Slides adapted from Steve Zdancewic

Announcements

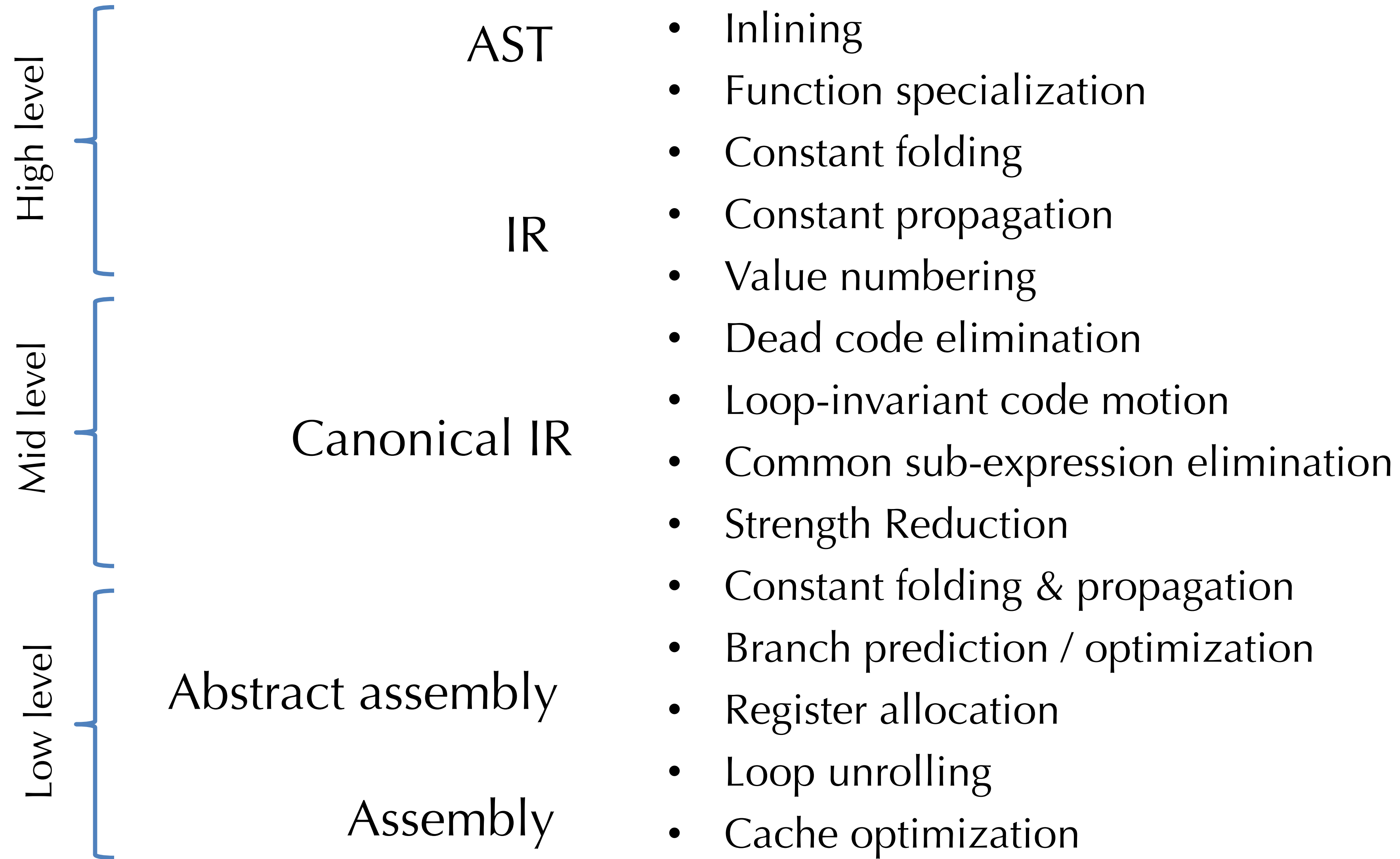
- Exam Grading almost done
- Assignment 4 due next Friday, April 4



Why optimize?

OPTIMIZATIONS, GENERALLY

When to apply optimization



Safety

- Whether an optimization is *safe* depends on the programming language semantics.
 - Languages that provide weaker guarantees to the programmer permit more optimizations but have more ambiguity in their behavior.
 - e.g., In C, loading from uninitialized memory is undefined, so the compiler can do anything if a program reads uninitialized data.
 - e.g., In Java tail-call optimization (which turns recursive function calls into loops) is not valid because of “stack inspection”.
- Example: *loop-invariant code motion*
 - Idea: hoist invariant code out of a loop

```
while (b) {  
  z = y/x;  
  ...           // y, x not updated  
}
```



```
z = y/x;  
while (b) {  
  ...           // y, x not updated  
}
```

- Is this more efficient?
- Is this safe?



A high-level tour of a variety of optimizations.

BASIC OPTIMIZATIONS

Constant Folding

- Idea: If operands are known at compile time, perform the operation statically.

`int x = (2 + 3) * y` → `int x = 5 * y`

`b & false` → `false`

- Performed at every stage of optimization...
- Why?
 - Constant expressions can be created by translation or earlier optimizations

Example: `A[2]` might be compiled to:

`MEM[MEM[A] + 2 * 4]` → `MEM[MEM[A] + 8]`

Constant Folding Conditionals

if (true) S → S

if (false) S → ;

if (true) S else S' → S

if (false) S else S' → S'

while (false) S → ;

if (2 > 3) S →

if (false) S → ;

Algebraic Simplification

- More general form of constant folding
 - Take advantage of mathematically sound simplification rules
- **Mathematical identities:**
 - $a * 1 \rightarrow a$ $a * 0 \rightarrow 0$
 - $a + 0 \rightarrow a$ $a - 0 \rightarrow a$
 - $b \mid \text{false} \rightarrow b$ $b \ \& \ \text{true} \rightarrow b$
- **Reassociation & commutativity:**
 - $(a + 1) + 2 \rightarrow a + (1 + 2) \rightarrow a + 3$
 - $(2 + a) + 4 \rightarrow (a + 2) + 4 \rightarrow a + (2 + 4) \rightarrow a + 6$
- **Strength reduction:** (replace expensive op with cheaper op)
 - $a * 4 \quad \rightarrow \quad a \ll 2$
 - $a * 7 \quad \rightarrow \quad (a \ll 3) - a$
 - $a / 32767 \rightarrow \quad (a \gg 15) + (a \gg 30)$
- *Note 1:* must be careful with floating point (due to rounding) and integer arithmetic (due to overflow/underflow)
- *Note 2:* iteration of these optimizations is useful... how much?
- *Note 3:* must be sure that rewrites terminate:
 - commutativity apply like: $(x + y) \rightarrow (y + x) \rightarrow (x + y) \rightarrow (y + x) \rightarrow \dots$

Constant Propagation

- If a variable is known to be a constant, replace the use of the variable by the constant
- Value of the variable must be propagated forward from the point of assignment
 - This is a *substitution* operation

Example:

```
int x = 5;  
int y = x * 2;  
int z = a[y];
```

 →

```
int y = 5 * 2;  
int z = a[y];
```

 →

```
int y = 10;  
int z = a[y];
```

 →

```
int z = a[10];
```

- To be most effective, constant propagation should be interleaved with constant folding

Copy Propagation

- If one variable is assigned to another, replace uses of the assigned variable with the copied variable.
- Need to know where copies of the variable propagate.
- Interacts with the scoping rules of the language.

- Example:

```
x = y;  
if (x > 1) {  
    x = x * f(x - 1);  
}
```

→

```
x = y;  
if (y > 1) {  
    x = y * f(y - 1);  
}
```

- Can make the first assignment to x **dead code** (that can be eliminated).

Dead Code Elimination

- If a side-effect free statement can never be observed, it is safe to eliminate the statement.

```
x = y * y // x is dead!  
...      // x never used  
x = z * z
```

```
→  
x = z * z ...
```

- A variable is **dead** if it is never used after it is defined.
 - Computing such *definition* and *use* information is an important component of program analysis
- Dead variables can be created by other optimizations...

Unreachable/Dead Code

- Basic blocks not reachable by any trace leading from the starting basic block are *unreachable* and can be deleted.
 - Performed at the IR or assembly level
 - Improves cache, TLB performance
- Dead code: similar to unreachable blocks.
 - A value might be computed but never subsequently used.
- Code for computing the value can be dropped
- But only if it's **pure**, *i.e.*, it has *no externally visible side effects*
 - Externally visible effects: raising an exception, modifying a global variable, going into an infinite loop, printing to standard output, sending a network packet, launching a rocket
 - Note: Pure functional languages (e.g., Haskell) make reasoning about the safety of optimizations (and code transformations in general) easier!

Inlining

- Replace a call to a function with the body of the function itself with arguments rewritten to be local variables:
- Example in C: inline `pow` into `g`

```
int g(int x) { return x + pow(x); }
int pow(int a) {
    var b = 1; var x = 0;
    while (x < a) {b = 2 * b; x = x + 1}
    return b;
}
```



```
int g(int x) {
    int a = x;
    int b = 1; int x2 = 0;
    while (x2 < a) {b = 2 * b; x2 = x2 + 1};
    tmp = b;
    return x + tmp;
}
```

note: renaming

- May need to rename variables to avoid *capture*
- Best done at the AST or relatively high-level IR.
- When is it profitable?
 - Eliminates the stack manipulation, jump, etc.
 - Can increase code size.
 - Enables further optimizations

Code Specialization

- Idea: create specialized versions of a function that is called from different places with different arguments.
- Example: specialize function f in:

```
class A implements I { int m() {...} }  
class B implements I { int m() {...} }  
int f(I x) { x.m(); }           // don't know which m  
A a = new A(); f(a);           // know it's A.m  
B b = new B(); f(b);           // know it's B.m
```

- f_A would have code specialized to dispatch to A.m
- f_B would have code specialized to dispatch to B.m
- You can also inline methods when the run-time type is known statically
 - Often just one class implements a method.

Common Subexpression Elimination

- *fold redundant computations together*
 - in some sense, it's the opposite of inlining
- Example:

```
a[i] = a[i] + 1
```

compiles to:

```
[a + i*4] = [a + i*4] + 1
```

Common subexpression elimination removes the redundant add and multiply:

```
t = a + i*4; [t] = [t] + 1
```

- For safety, you must be sure that the shared expression always has the same value in both places!

Unsafe Common Subexpression Elimination

- Example: consider this C function:

```
unit f(int[] a, int[] b, int[] c) {  
    var j = ...; var i = ...; var k = ...;  
    b[j] = a[i] + 1;  
    c[k] = a[i];  
    return;  
}
```

- The optimization that shares the expression `a[i]` is unsafe... why?

```
unit f(int[] a, int[] b, int[] c) {  
    var j = ...; var i = ...; var k = ...;  
    t = a[i];  
    b[j] = t + 1;  
    c[k] = t;  
    return;  
}
```



LOOP OPTIMIZATIONS

Loop Optimizations

- Program hot spots often occur in loops.
 - Especially inner loops
 - Not always: consider operating systems code or compilers vs. a computer game or word processor
- Most program execution time occurs in loops.
 - The 90/10 rule of thumb holds here too.
(90% of the execution time is spent in 10% of the code)
- Loop optimizations are very important, effective, and numerous
 - Also, concentrating effort to improve loop body code is usually a win

Loop Invariant Code Motion (revisited)

- Another form of redundancy elimination.
- If the result of a statement or expression does not change during the loop *and* it's pure, it can be hoisted outside the loop body.
- Often useful for array element addressing code
 - Invariant code not visible at the source level

```
for (i = 0; i < a.length; i++) {  
    /* a not modified in the body */  
}
```



```
t = a.length;  
for (i = 0; i < t; i++) {  
    /* same body as above */  
}
```

Hoisted loop-
invariant
expression

Strength Reduction (revisited)

- Strength reduction can work for loops too
- Idea: replace expensive operations (multiplies, divides) by cheap ones (adds and subtracts)
- For loops, create a *dependent induction variable*:
- Example:

```
for (int i = 0; i < n; i++) { a[i*3] = 1; } // stride by 3
```



```
int j = 0;  
for (int i = 0; i < n; i++) {  
    a[j] = 1;  
    j = j + 3; // replace multiply by add  
}
```

Loop Unrolling (revisited)

- Branches can be expensive, unroll loops to avoid them.

```
for (int i=0; i<n; i++) { S }
```



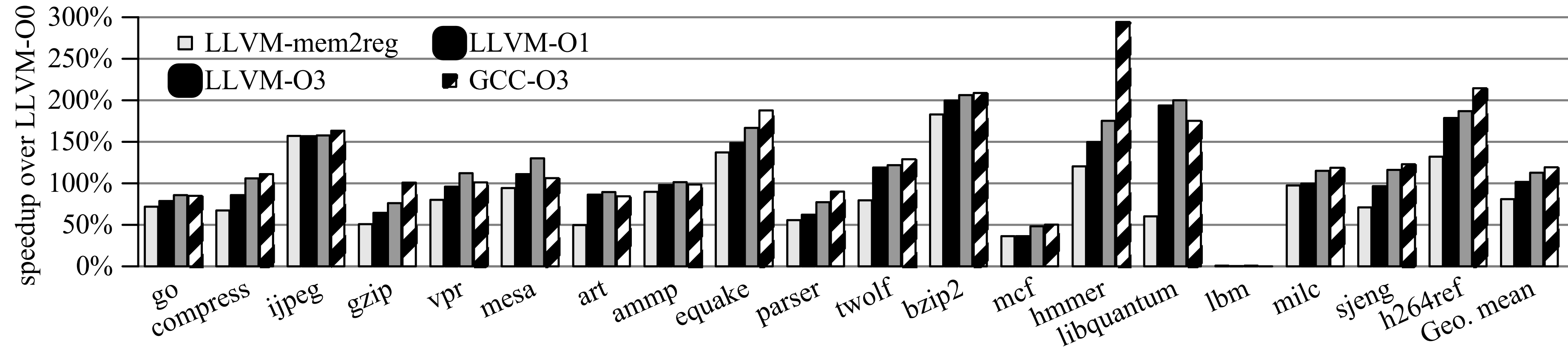
```
for (int i=0; i<n-3; i+=4) {S;S;S;S};  
for (    ; i<n; i++) { S } // left over iterations
```

- With k unrollings, eliminates $(k-1)/k$ conditional branches
 - So for the above program, it eliminates $3/4$ of the branches
- Space-time tradeoff:
 - Not a good idea for large S or small n
- Interacts with instruction caching, branch prediction



EFFECTIVENESS?

Optimization Effectiveness?



$$\% \text{speedup} = \left[\frac{\text{base time}}{\text{optimized time}} - 1 \right] \times 100\%$$

Example:

base time = 2s

optimized time = 1s

⇒

100% speedup

Example:

base time = 1.2s

optimized time = 0.87s

⇒

38% speedup

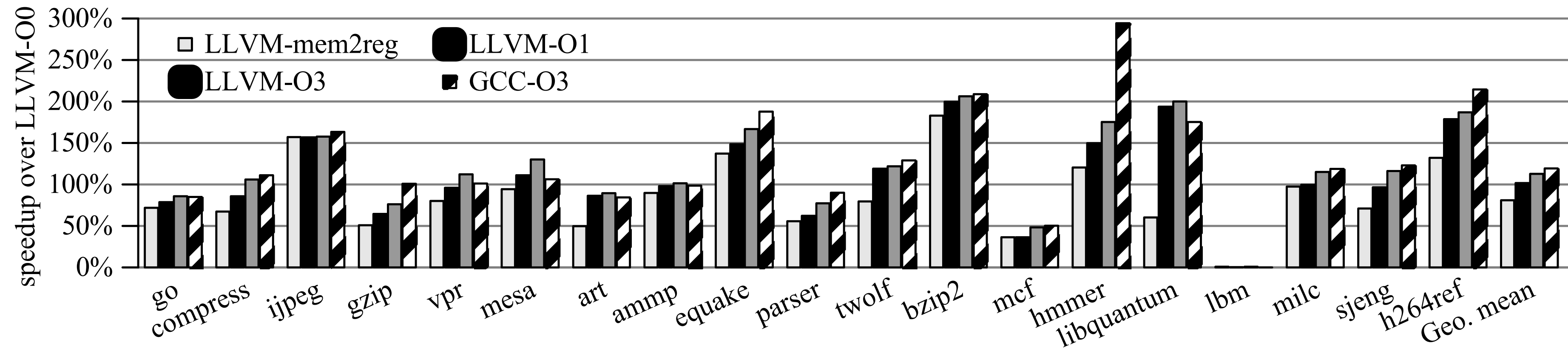
Graph taken from:

Jianzhou Zhao, Santosh Nagarakatte, Milo M. K. Martin, and Steve Zdancewic.

Formal Verification of SSA-Based Optimizations for LLVM.

In Proc. 2013 ACM SIGPLAN Conference on Programming Languages Design and Implementation (PLDI), 2013

Optimization Effectiveness?



- mem2reg: promotes alloca'ed stack slots to temporaries to enable register allocation
- Analysis:
 - mem2reg alone (+ back-end optimizations like register allocation) yields ~78% speedup on average
 - -O1 yields ~100% speedup (so all the rest of the optimizations combined account for ~22%)
 - -O3 yields ~120% speedup
- Hypothetical program that takes 10 sec. (base time):
 - Mem2reg alone: expect ~5.6 sec
 - -O1: expect ~5 sec
 - -O3: expect ~4.5 sec



CODE ANALYSIS

Motivating Code Analyses

- There are lots of things that might influence the safety/applicability of an optimization
 - What algorithms and data structures can help?
- How do you know what is a loop?
- How do you know an expression is invariant?
- How do you know if an expression has no side effects?
- How do you keep track of where a variable is defined?
- How do you know where a variable is used?
- How do you know if two reference values may be aliases of one another?

Assertion Removal

- Dynamic typing adds many runtime assertions into our program.
- ```
let x = g() in
let y = x + 2 in
let z = y * x in
...
```
- Current compilation always adds assertions that inputs are integers
- ```
x = g()  
assertInt(x)  
y = x + 2  
assertInt(y)  
assertInt(x)  
y2 = y >> 1  
z = y2 * x  
...
```
- Which assertions can we remove?

Tag-checking Analysis

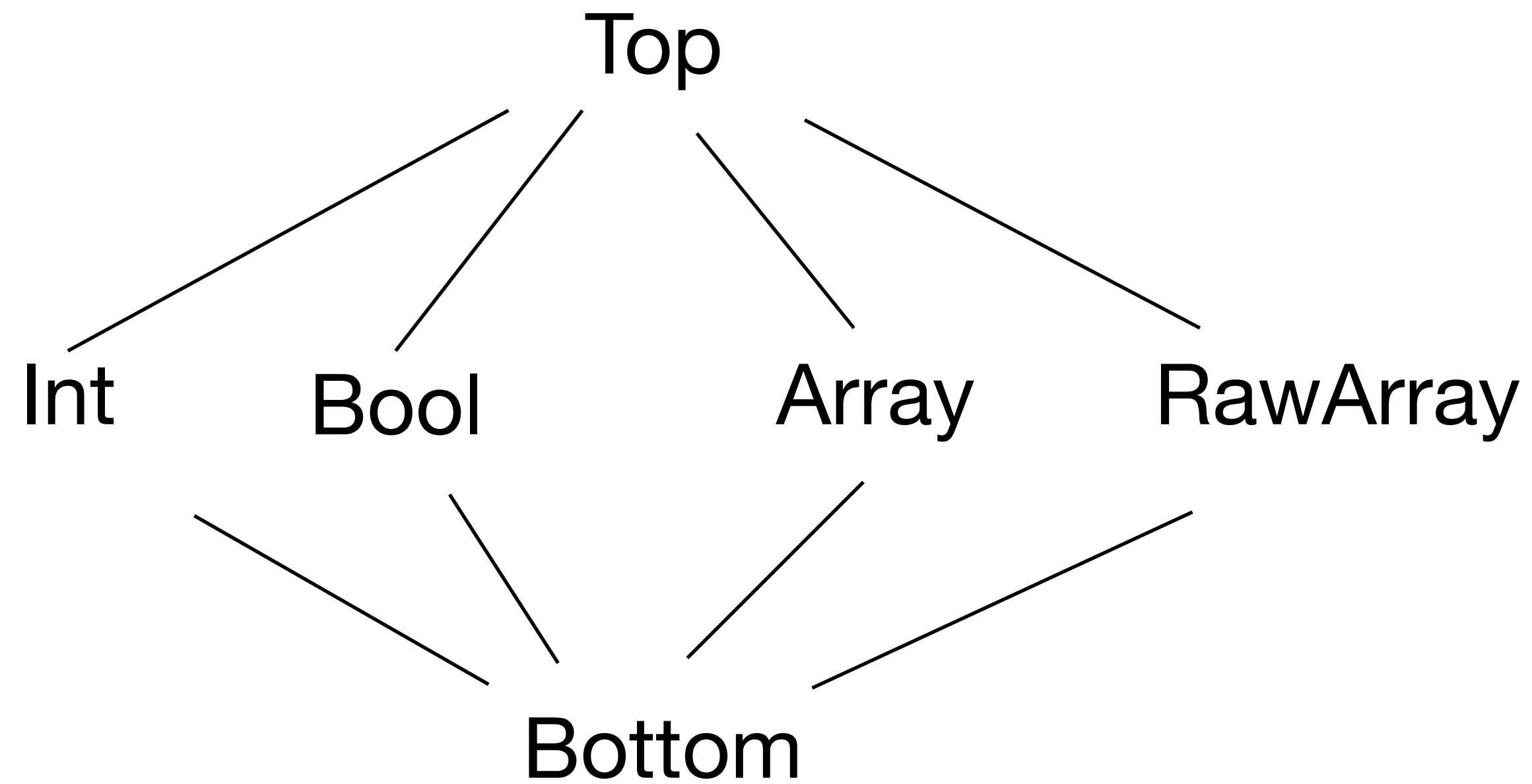
- At each program point, for each variable associate an approximation of what the possible values are:
 - Int: tagged integer, i.e., multiple of 2
 - Bool: tagged boolean, i.e., either 0b001 or 0b101
 - RawArray: untagged pointer to an array on the heap
 - Array: tagged array, i.e., a pointer tagged with 0b11
 - Top: any 64 bit value
 - Bottom: never assigned to, i.e., uninitialized
- Usage: If analysis determines x is an Int, then remove assertions `assertInt(x)`

similar for `assertArray`, `assertBool` etc.

Tag-checking Analysis

most possibilities

fewest possibilities



Straightline Code Example

```
x = f()  
assertInt(x)  
y = x + 2  
assertInt(y)  
assertInt(x)  
y2 = y >> 1  
z = y2 * x
```

Tag-checking Analysis

- For each operation in SSA, need to define "flow function" that says what possible tags are based on inputs.

Examples:

- $x = y + z$
 - if y and z are tagged Ints, then x is a tagged Int
 - otherwise x is Top
- $x = y * z$
 - if y or z is a tagged Int then x is a tagged Int
 - otherwise Top
- $x = y \ll n$
 - if n is at least 1 then x is tagged Int
 - if n is 0, then x is tagged if y is
- `assertInt(x)`
 - after this, x is always a tagged Int, because otherwise execution ended

Straightline Code Example

```
0 x = f()  
1 assertInt(x)  
2 y = x + 2  
3 assertInt(y)  
4 assertInt(x)  
5 y2 = y >> 1  
6 z = y2 * x  
7
```

```
0:  
1: {x: Top}  
2: {x: Int}  
3: {x: Int, y: Int}  
4: {x: Int, y: Int}  
5: {x: Int, y: Int}  
6: {x: Int, y: Int, y2: Top}  
7: {x: Int, y: Int, y2: Top, z: Int}
```

Straightline Code Example

```
0 x = f()  
1 assertInt(x)  
2 y = x + 2  
3 assertInt(y)  
4 assertInt(x)  
5 y2 = y >> 1  
6 z = y2 * x  
7
```

```
0:  
1: {x: Top}  
2: {x: Int}  
3: {x: Int, y: Int}  
4: {x: Int, y: Int}  
5: {x: Int, y: Int}  
6: {x: Int, y: Int, y2: Top}  
7: {x: Int, y: Int, y2: Top, z: Int}
```