



EECS 483: Compiler Construction

Lecture 14:

Memory Management, Garbage Collection

**March 10
Winter Semester 2025**

Slides adapted from David Walker, Cornell University

Announcements

Midterm on Tuesday, March 18, 6-8pm.

Topics: anything covered in assignments 1-3 and lecture material before spring break

Rooms DOW1010, DOW1017, DOW1018

Midterm review in lecture **March 12** (previously said March 17) and in Discussion this week bring questions about course material.

Assignment 4 (dynamic typing, heap allocation) released after the midterm

Memory Deallocation and Reuse

- Every modern programming language allows programmers to allocate new storage dynamically
 - New records, arrays, tuples, objects, closures, etc.
- Every modern language needs facilities for **reclaiming and recycling** the storage used by programs
- It's usually the most complex aspect of the run-time system for any modern language.

Memory Deallocation and Reuse

- Memory used for an object can be reused if it is **garbage**
- What is **garbage**?
 - A value is garbage if it **will not be used** in any subsequent computation by the program
- How do we determine which objects are garbage?

Identifying Garbage

- How do we determine which objects are garbage?
- Stack-allocation:
 - when we return or tail call, all objects in the stack frame are garbage so that memory can be reused.
 - See: our implementation of return, branch with arguments
 - this is an **under-approximation**. Objects allocated on the stack may remain long after they are no longer used.
- Is it easy to determine which objects are garbage?
 - No. It's undecidable. Eg:
 - if long-and-tricky-computation then use v
 - else don't use v

Identifying Garbage

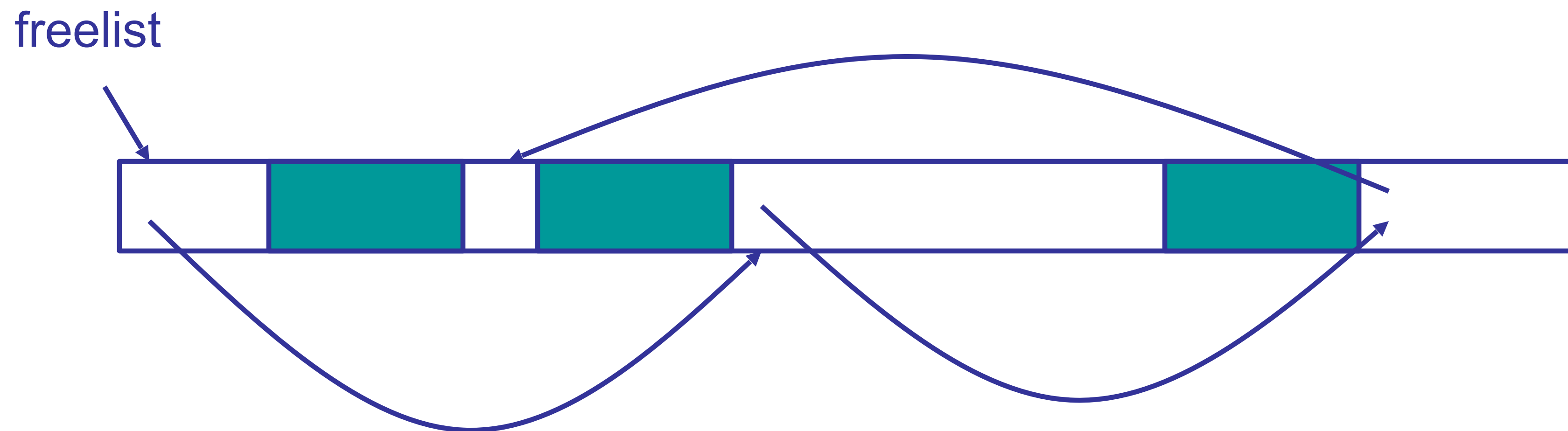
- Since determining which objects are garbage is tricky, people have come up with many different techniques
 - It's the programmers problem:
 - Explicit allocation/deallocation
 - Reference counting
 - Tracing garbage collection
 - Mark-sweep, copying collection
 - Generational GC

Explicit MM

- User library manages memory; programmer decides when and where to allocate and deallocate
 - `void* malloc(long n)`
 - `void free(void *addr)`
 - Library calls OS for more pages when necessary
 - Advantage: if you work hard, you can free at the exact right time for their program
 - Disadvantage: people don't want to bother with such details if they can avoid it
 - Disadvantage: difficult to get right, dangerous when wrong

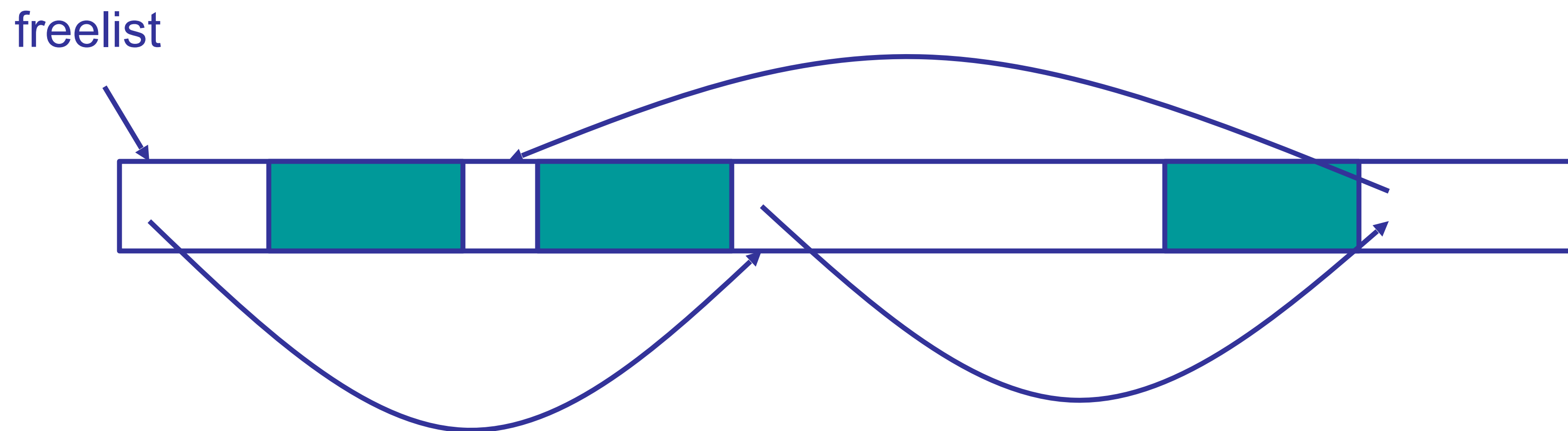
Explicit MM

- How does malloc/free work?
 - Blocks of unused memory stored on a **freelist**
 - **malloc**: search free list for usable memory block
 - **free**: put block onto the head of the freelist



Explicit MM

- Drawbacks
 - **malloc is not free**: we might have to do a significant search to find a big enough block
 - As program runs, the heap **fragments** leaving many small, unusable pieces



Explicit MM

- Solutions:
 - Use multiple free lists, one for each block size
 - Malloc and free become $O(1)$
 - But can run out of size 4 blocks, even though there are many size 6 blocks or size 2 blocks!
 - Blocks are powers of 2
 - Subdivide blocks to get the right size
 - Adjacent free blocks merged into the next biggest size
 - Still doesn't avoid **fragmentation**
 - 30% wasted space
 - No magic bullet: memory management always has a cost

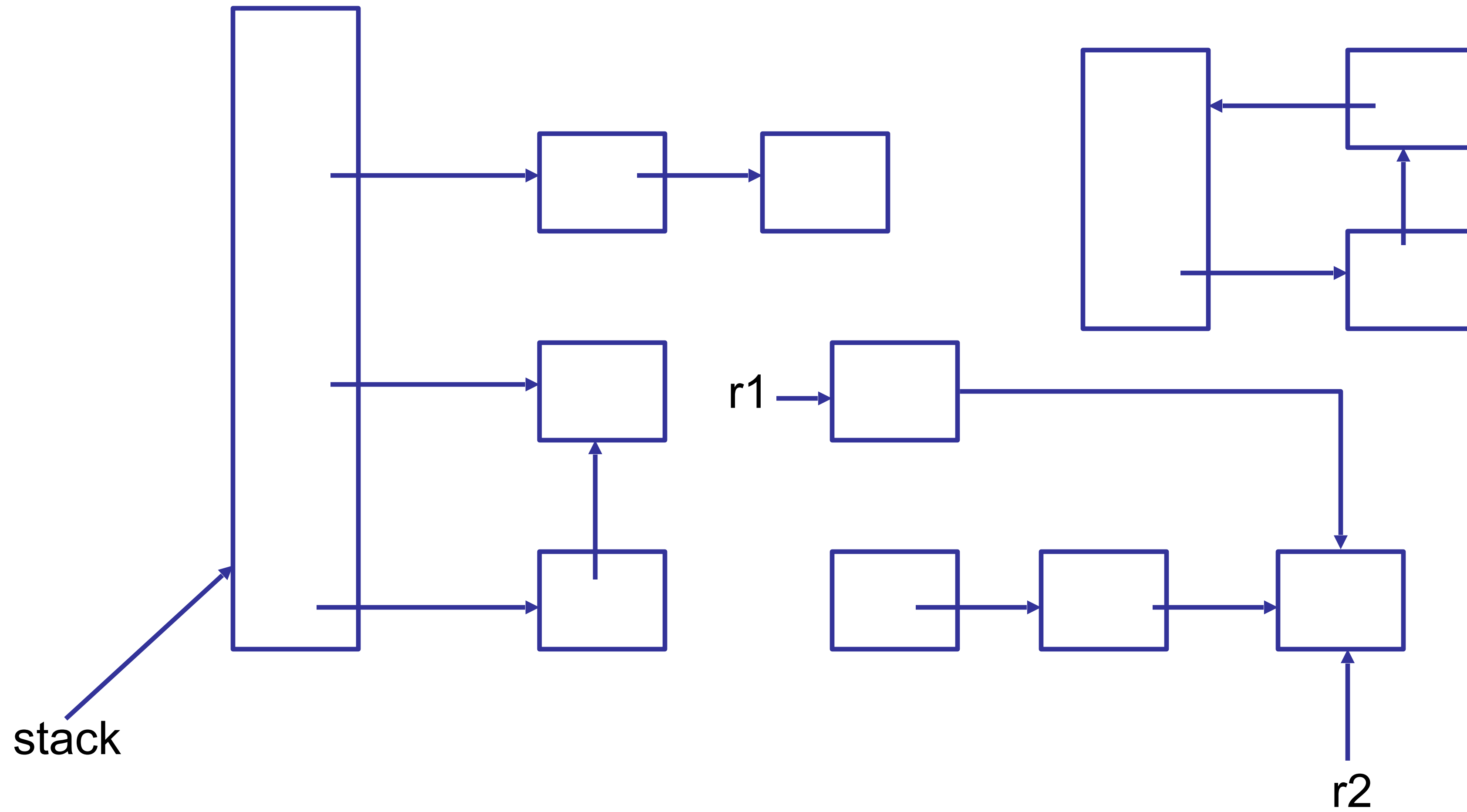
Automatic MM

- Languages with explicit MM are much harder to program than languages with automatic MM
 - Always worrying about **dangling pointers**, **memory leaks**: a huge software engineering burden with mistakes often leading to **security vulnerabilities**
 - Languages with unsafe, explicit MM are on the way out. Alternatives like Rust are being incorporated into high-performance settings like Linux kernel and web browsers.
 - Biden administration even instituted an executive order recommending new software be written in memory-safe languages!

Automatic MM

- Question: how do we decide which objects are garbage?
 - We **conservatively approximate**
 - Normal solution: an object is garbage when it becomes **unreachable** from the **roots**
 - The **roots** = registers, stack, global static data
 - If there is no path from the roots to an object, it cannot be used later in the computation so we can safely recycle its memory

Object Graph

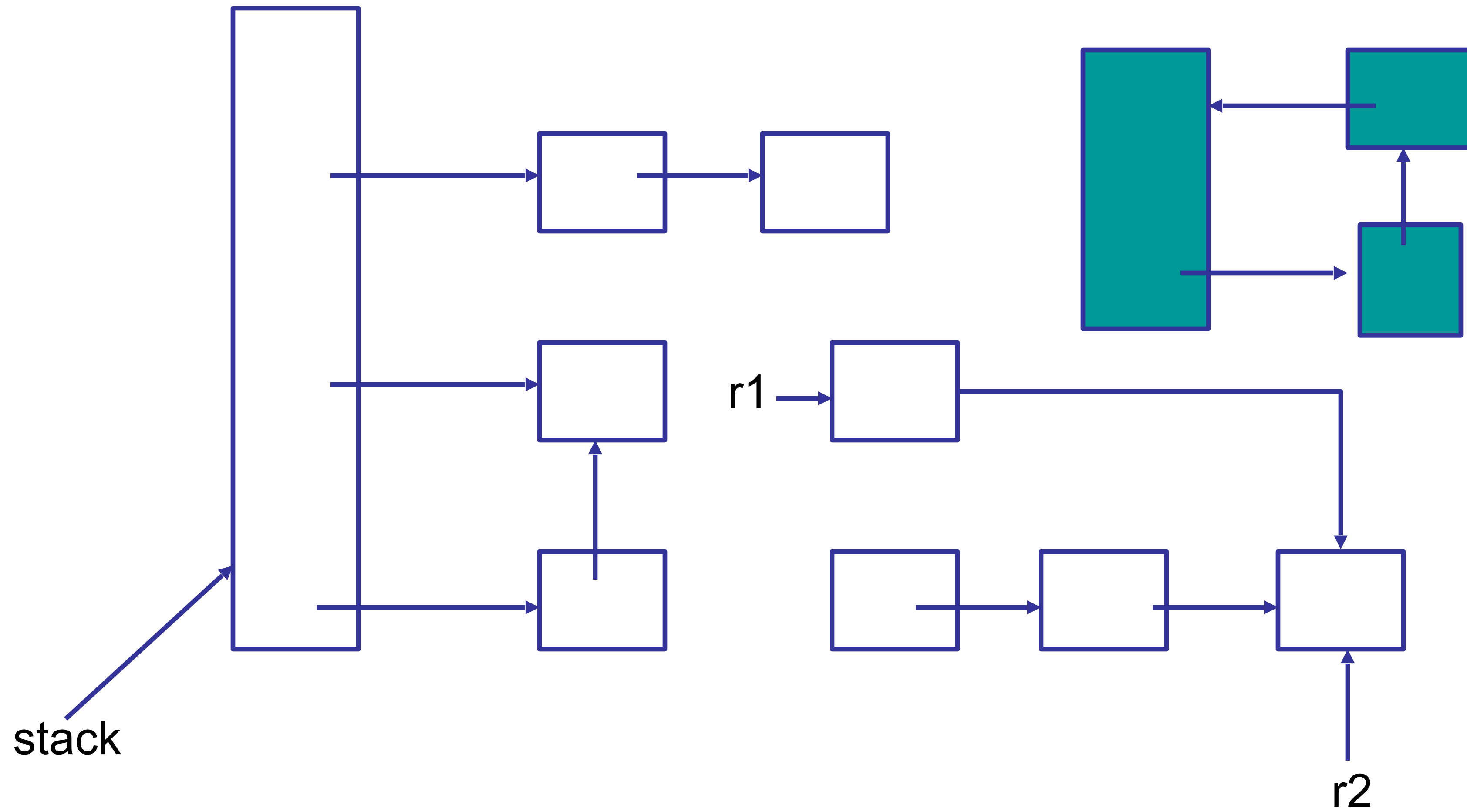


– How should we test reachability?

Reference Counting

- Keep track of the number of pointers to each object (**the reference count**).
- When the reference count goes to 0, the object is unreachable garbage

Object Graph



– Reference counting can't detect cycles

Reference Counting

– In place of a single assignment $x.f = p$:

$z = x.f$

$c = z.count$

$c = c - 1$

$z.count = c$

If $c = 0$ call `putOnFreeList(z)`

$x.f = p$

$c = p.count$

$c = c + 1$

$p.Count = c$

- Ouch, *that hurts*

performance-wise!

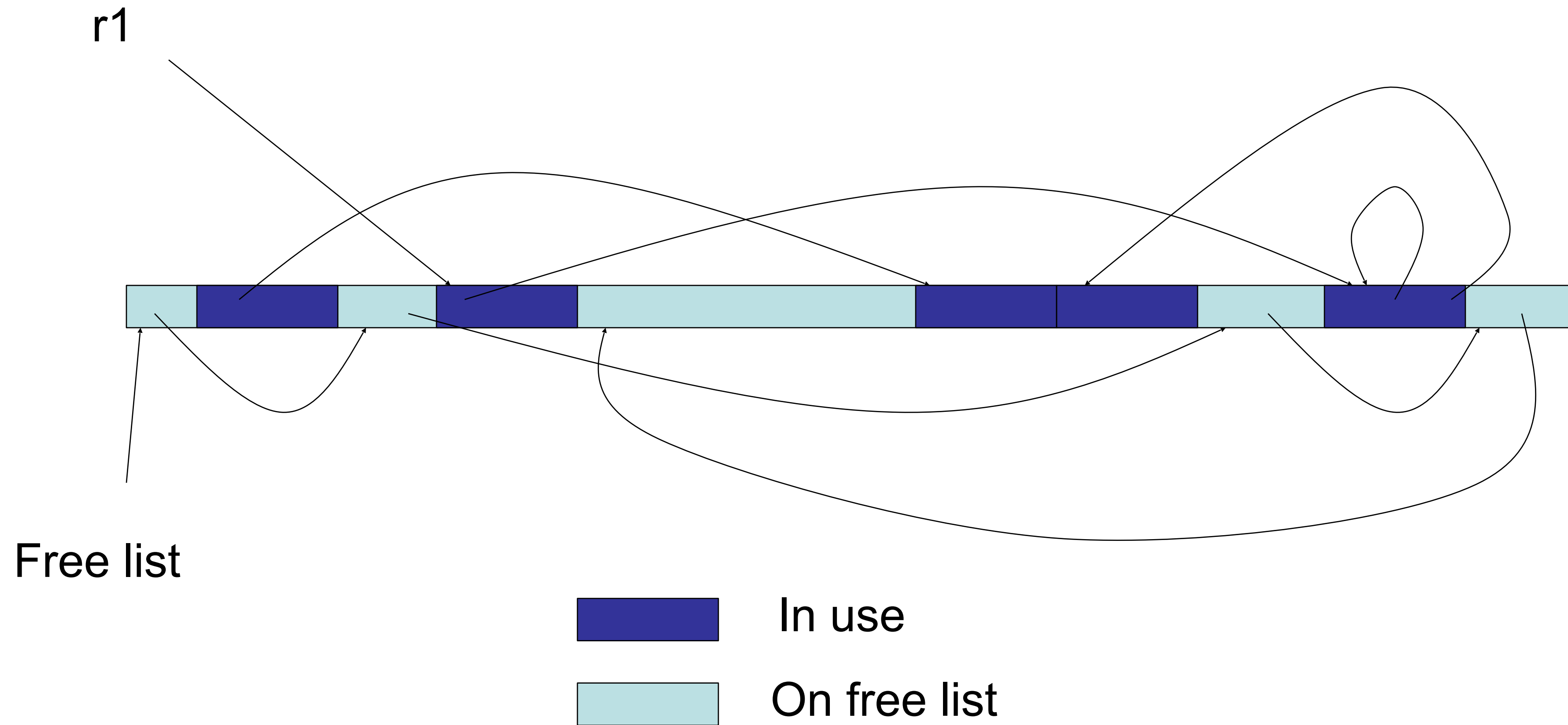
- *Dataflow analysis* can eliminate some increments and decrements, but many remain

- Reference counting used in some special cases but not usually as the primary GC mechanism in a language implementation

Mark-sweep

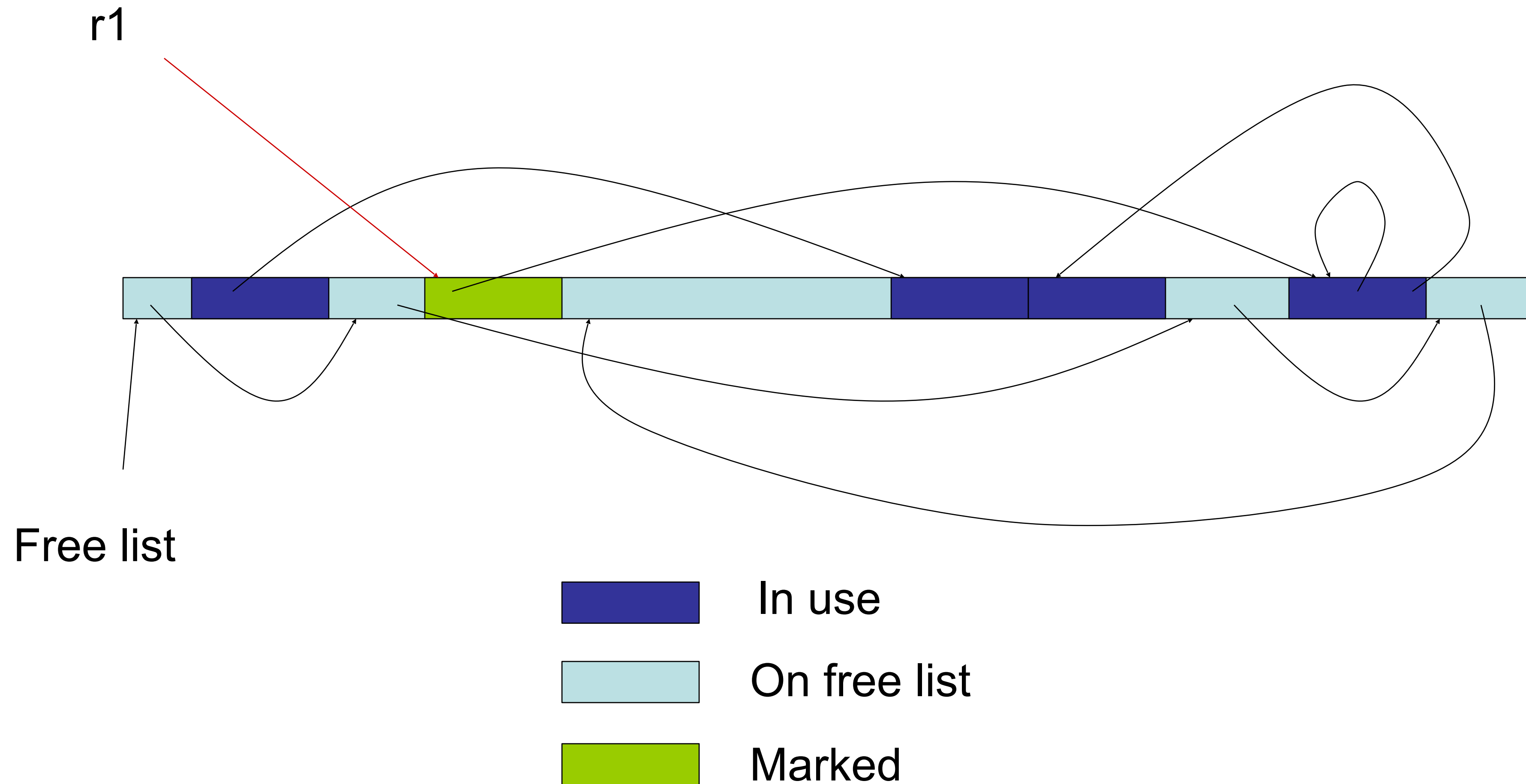
- A two-phase algorithm
 - **Mark phase**: Depth first traversal of object graph from the roots to mark live data
 - **Sweep phase**: iterate over entire heap, adding the unmarked data back onto the free list

Example



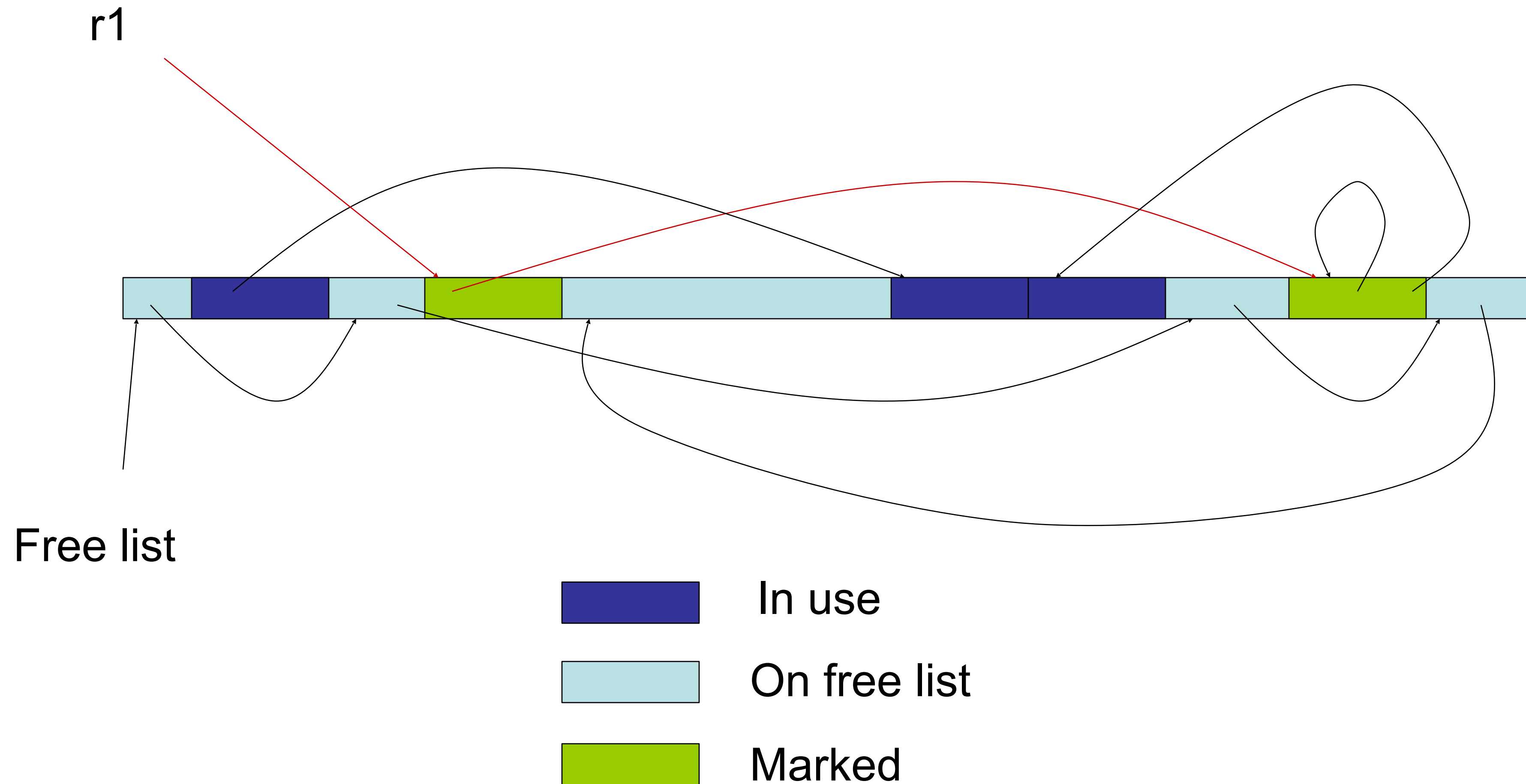
Example

Mark Phase: mark nodes reachable from roots



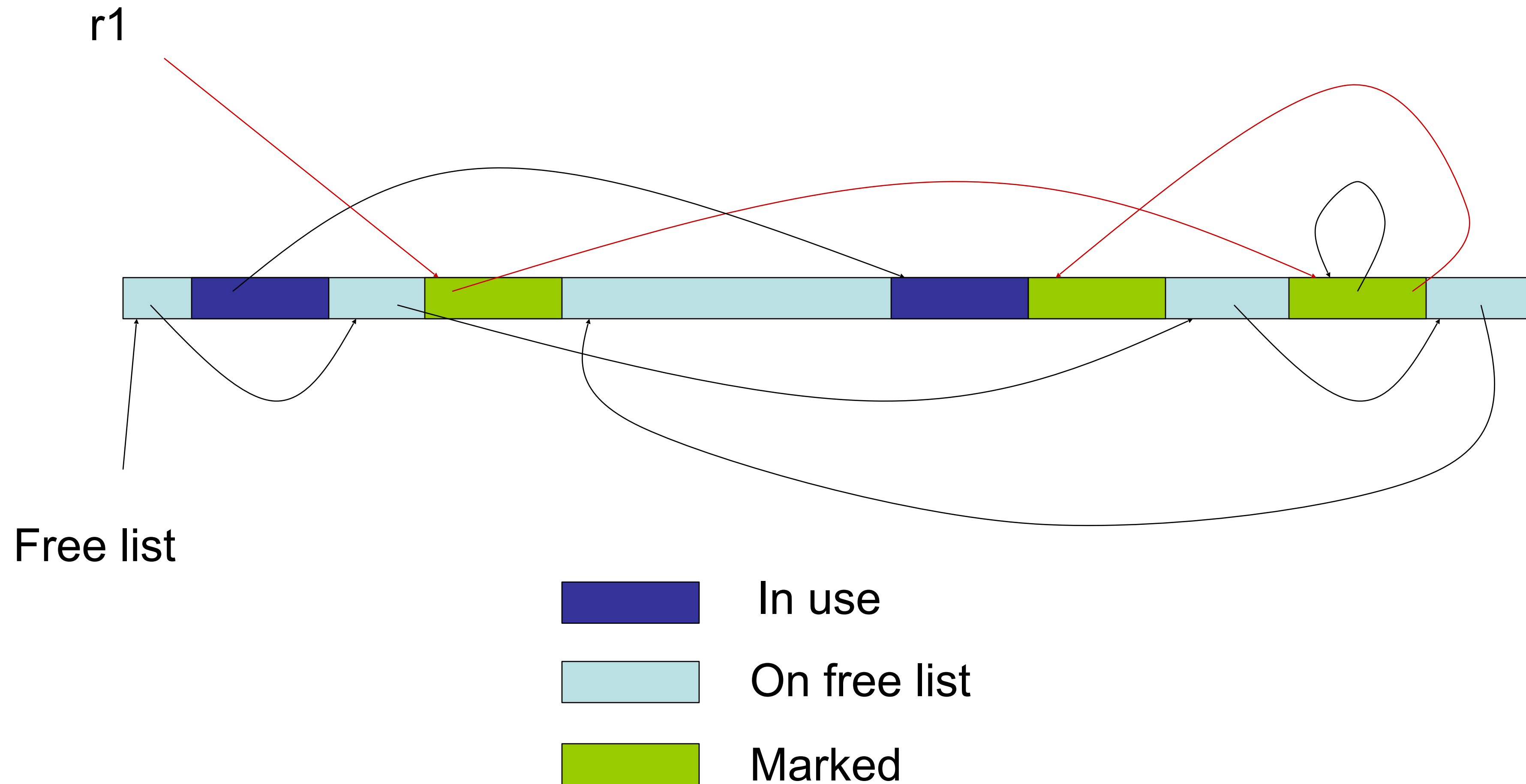
Example

Mark Phase: mark nodes reachable from roots



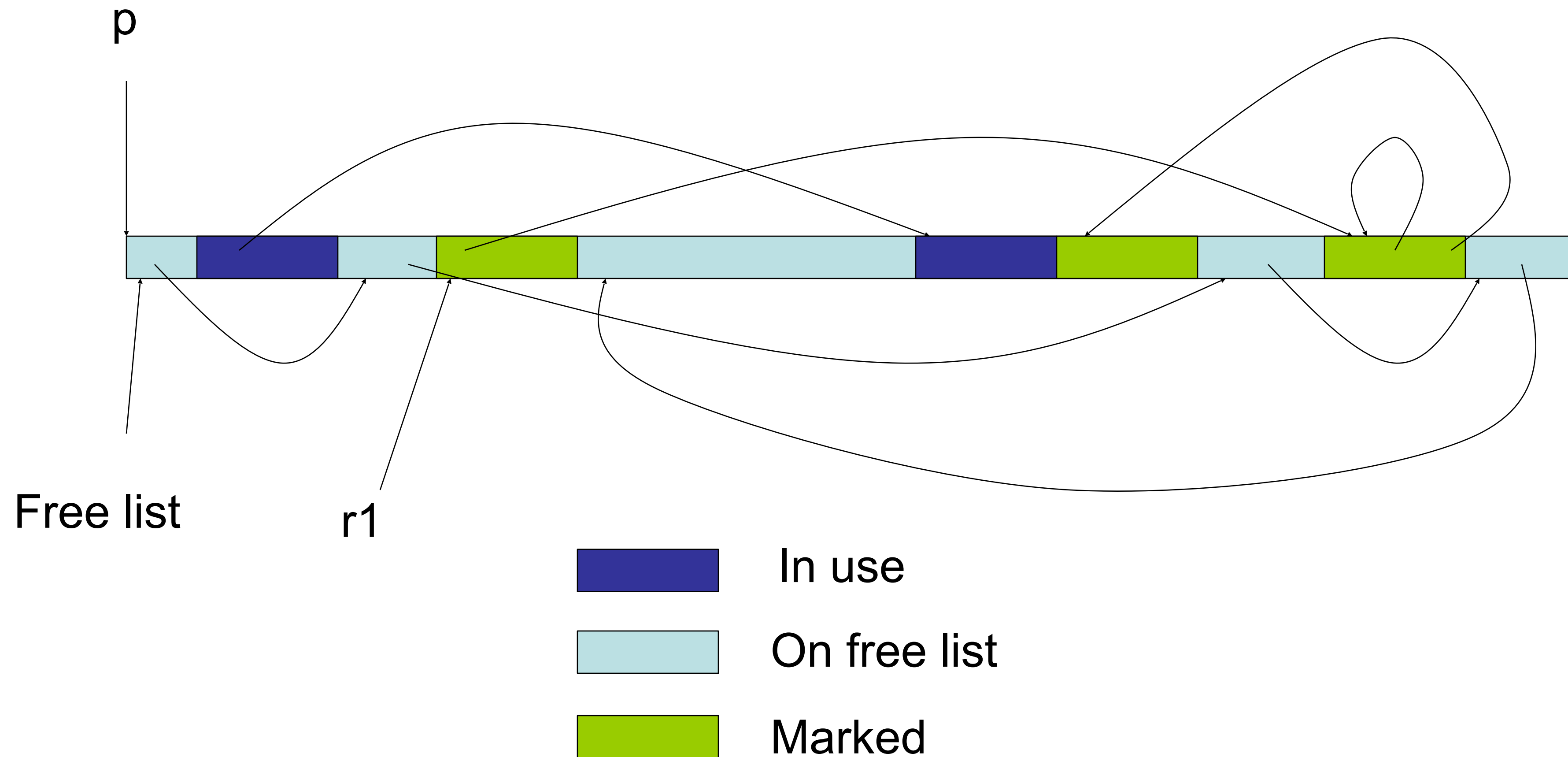
Example

Mark Phase: mark nodes reachable from roots



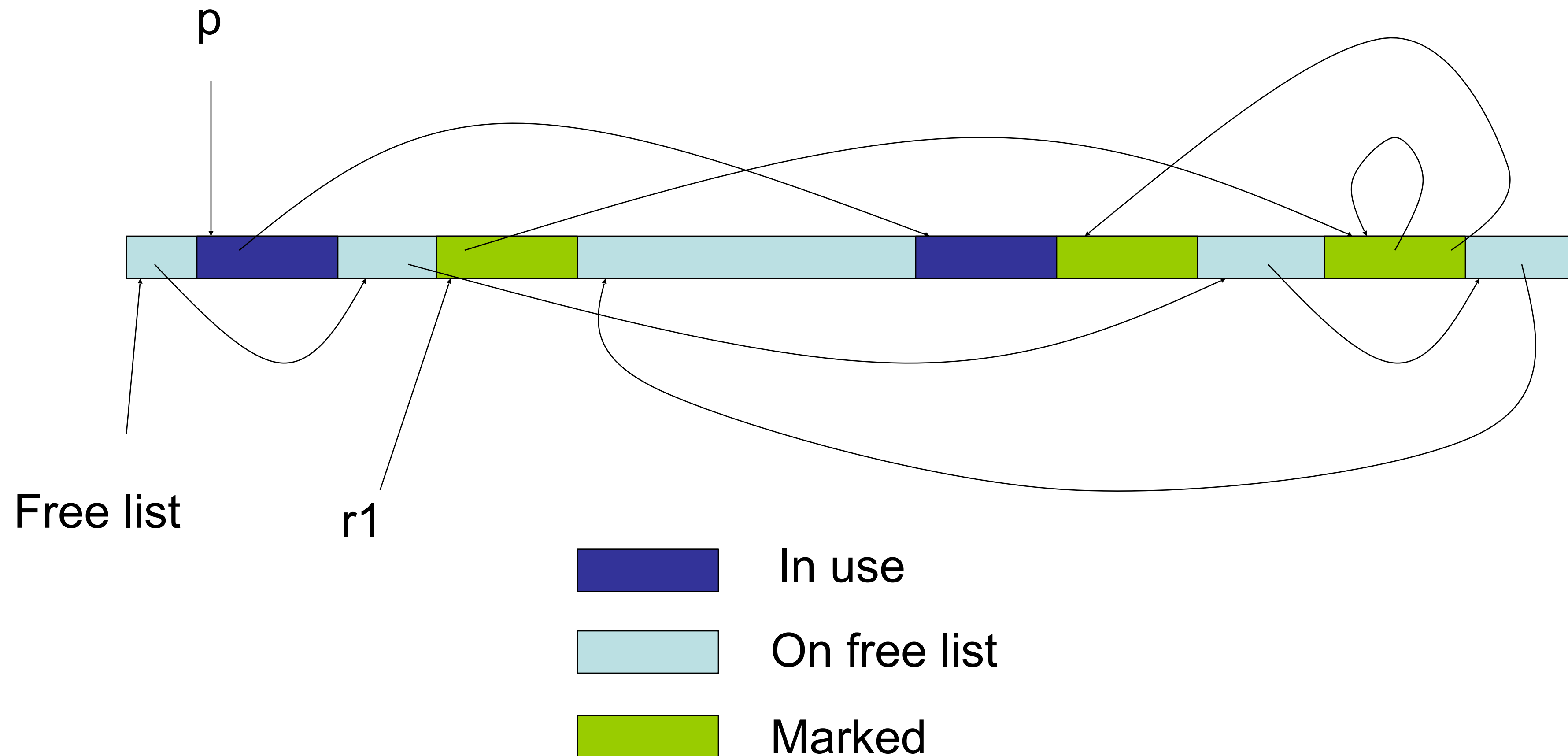
Example

Sweep Phase: set up sweep pointer; begin sweep



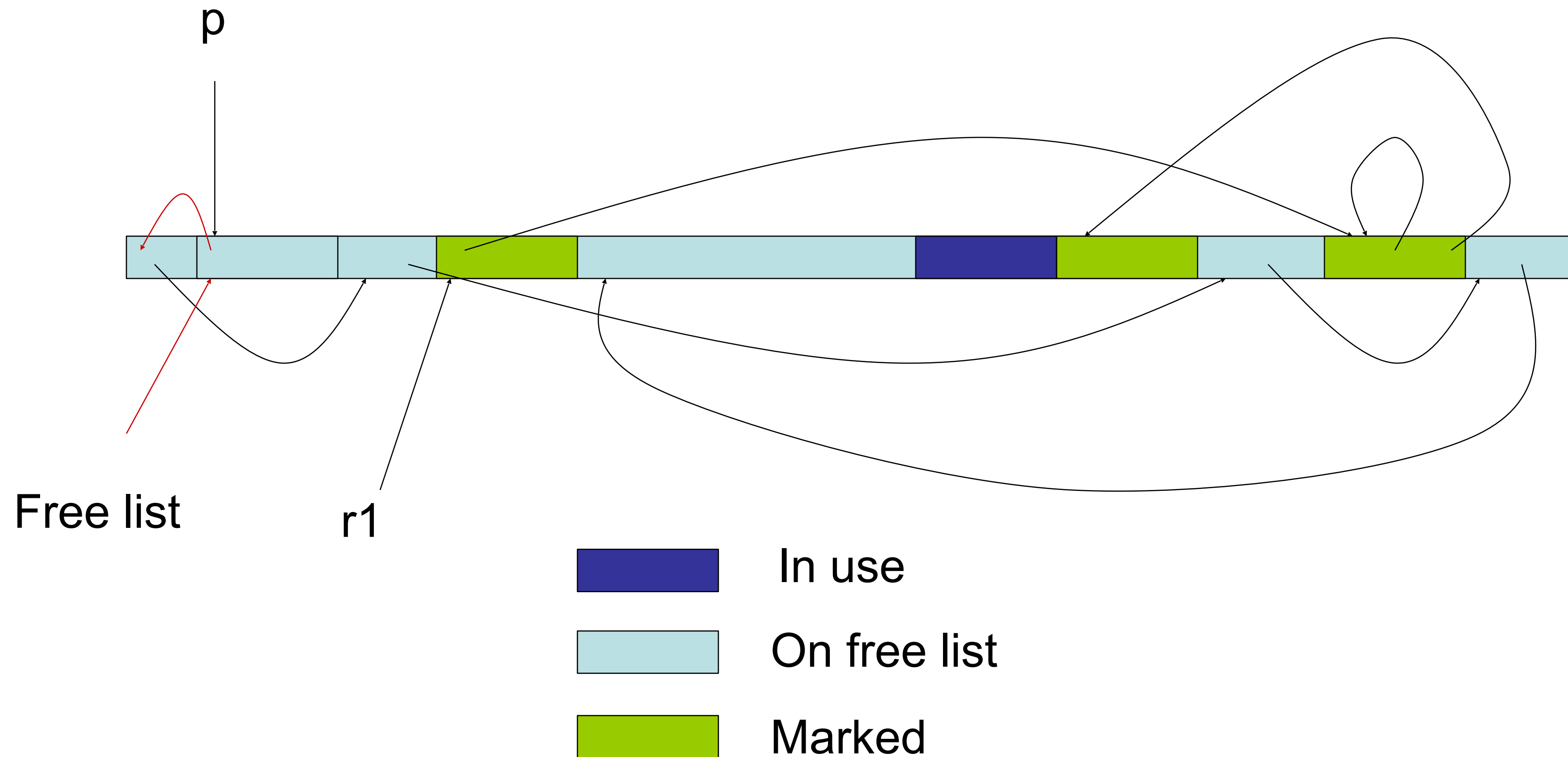
Example

Sweep Phase: add unmarked blocks to free list



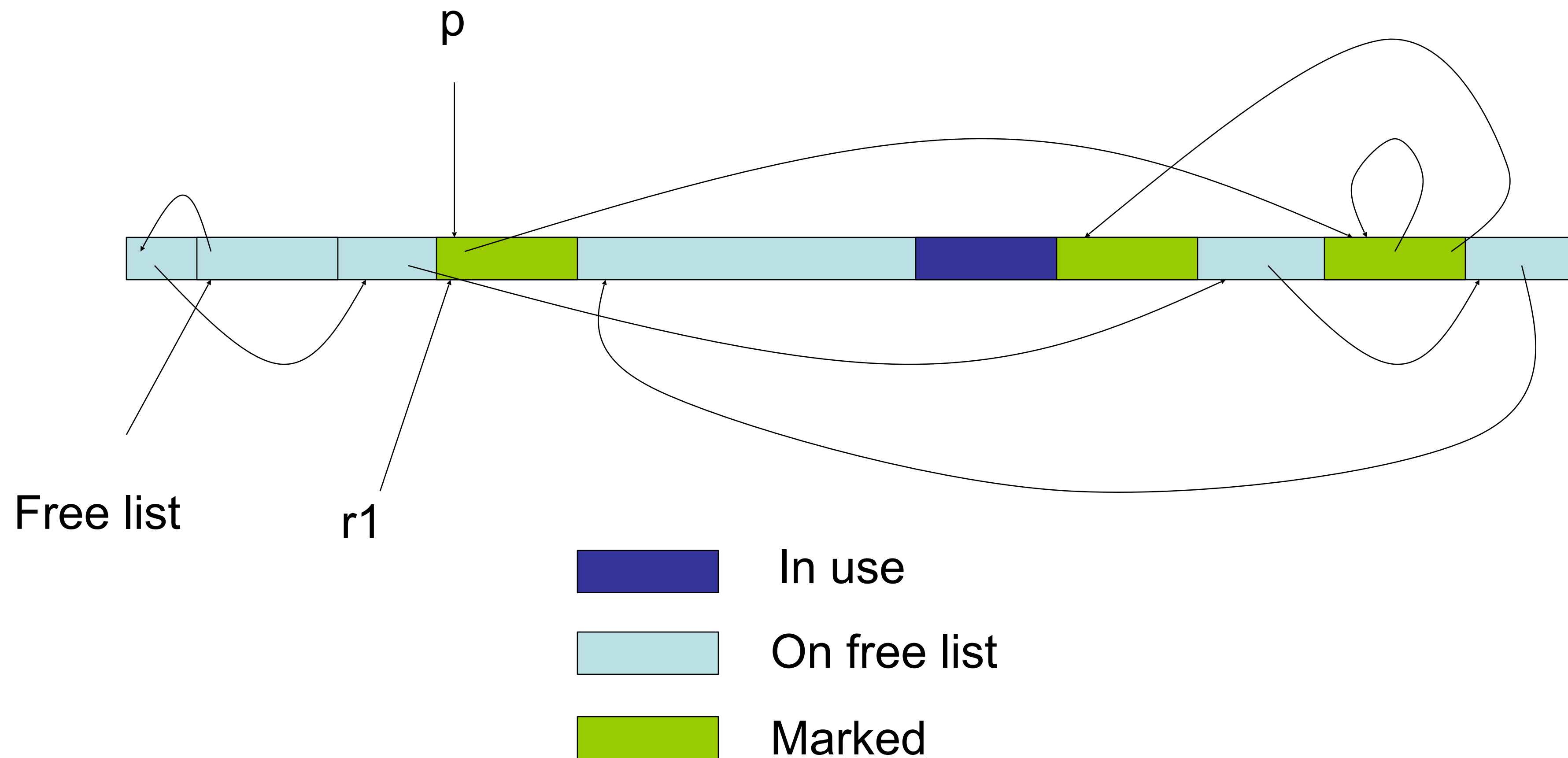
Example

Sweep Phase



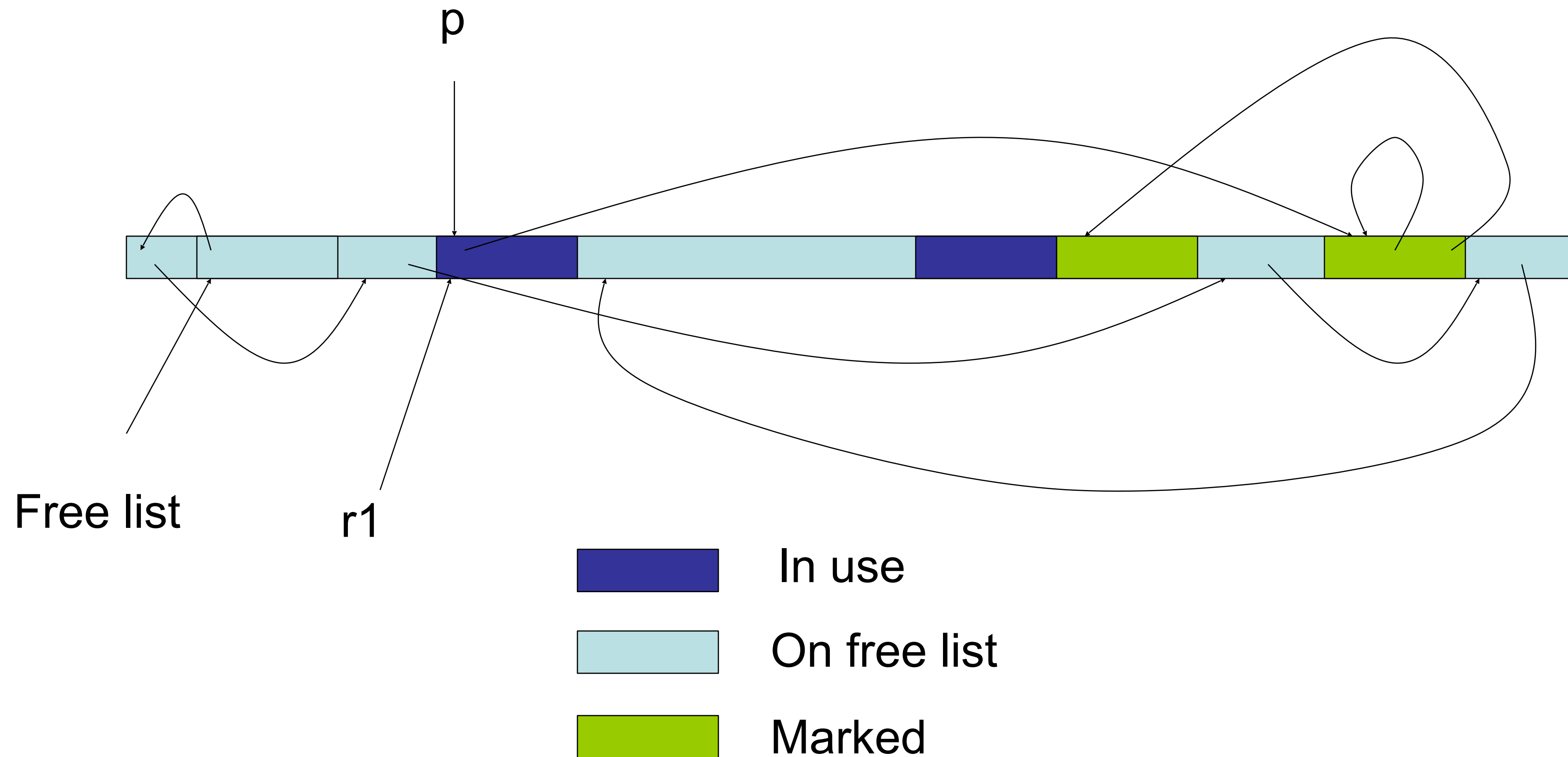
Example

Sweep Phase: retain & unmark marked blocks



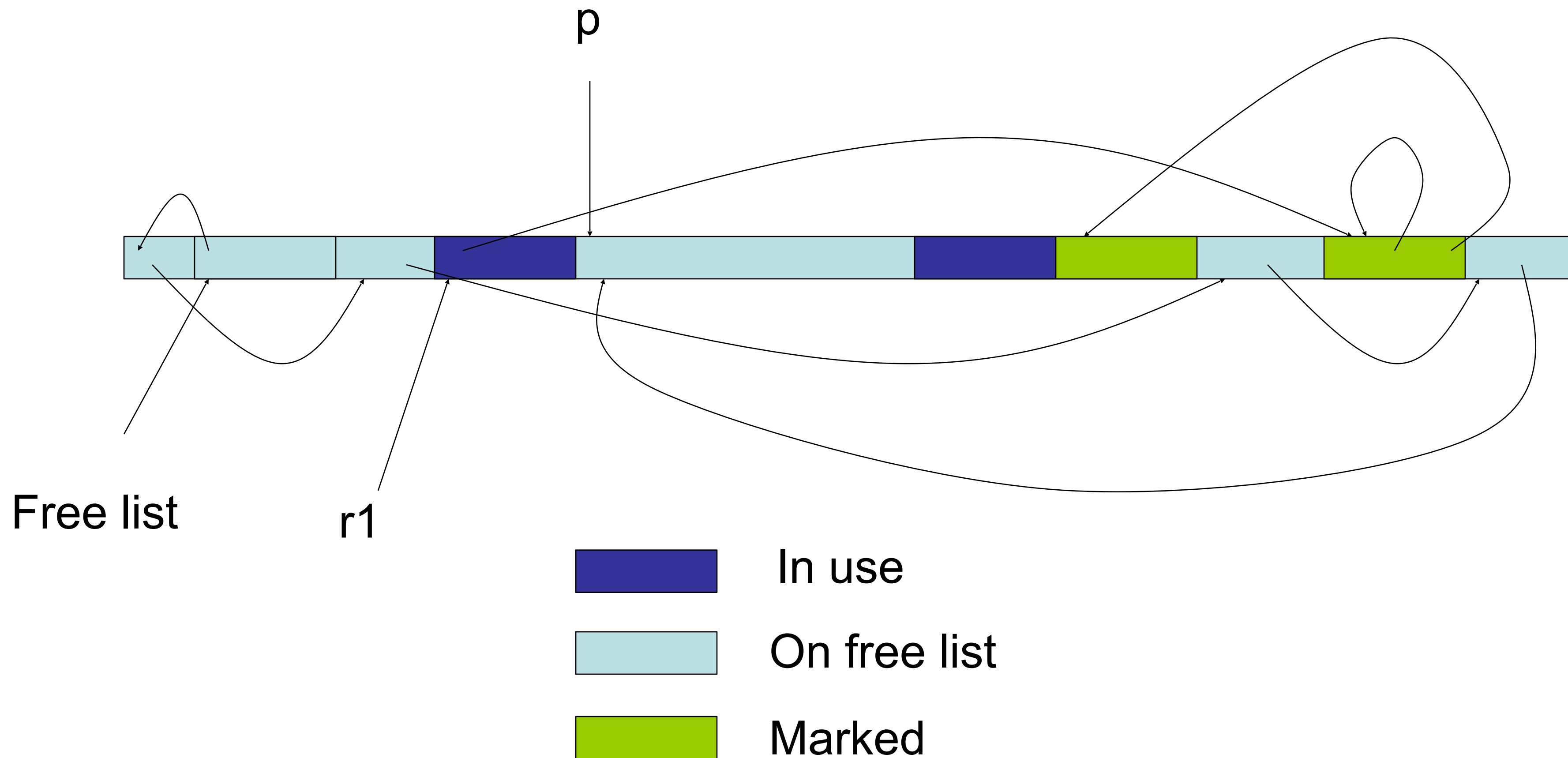
Example

Sweep Phase



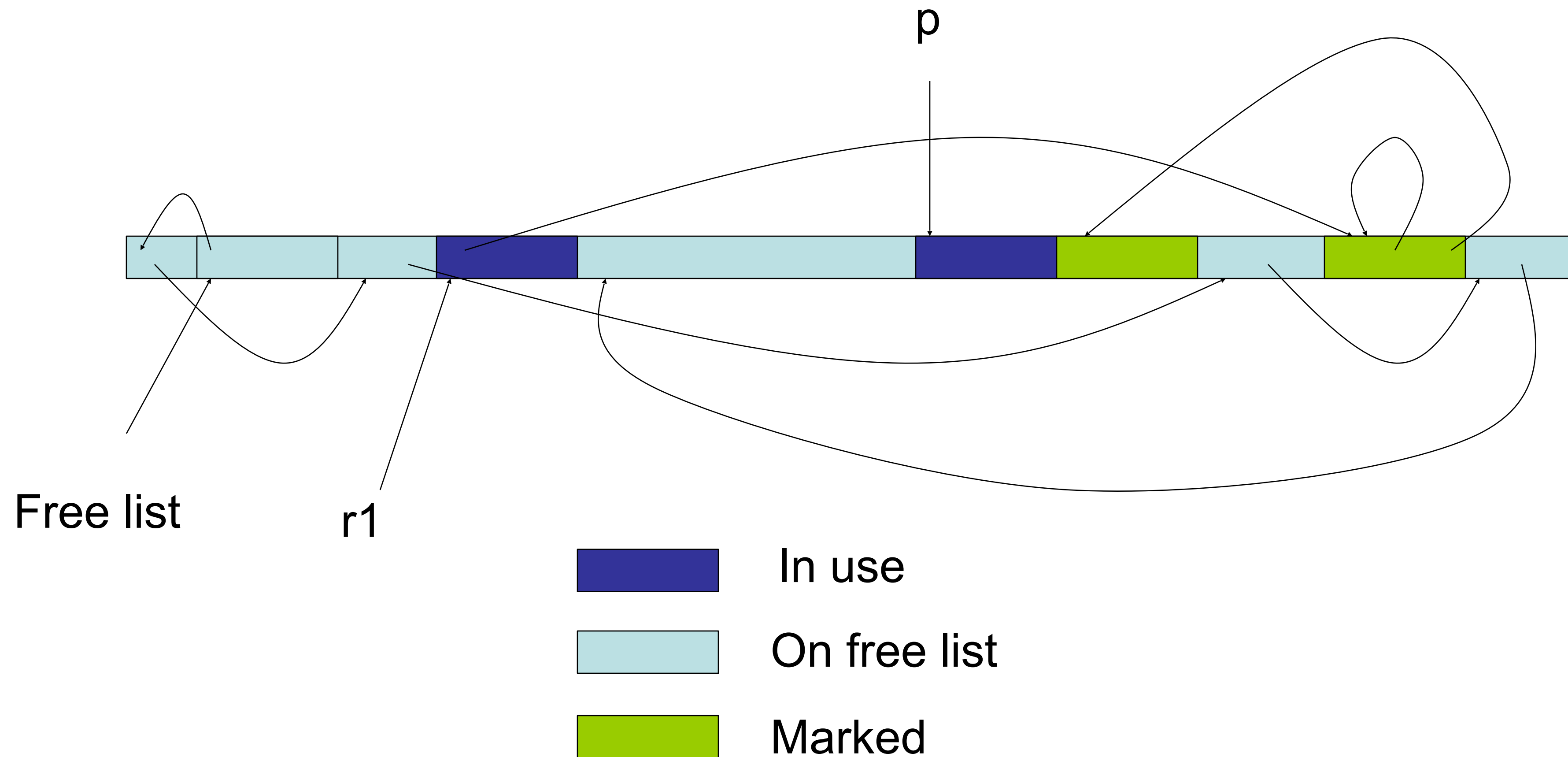
Example

Sweep Phase



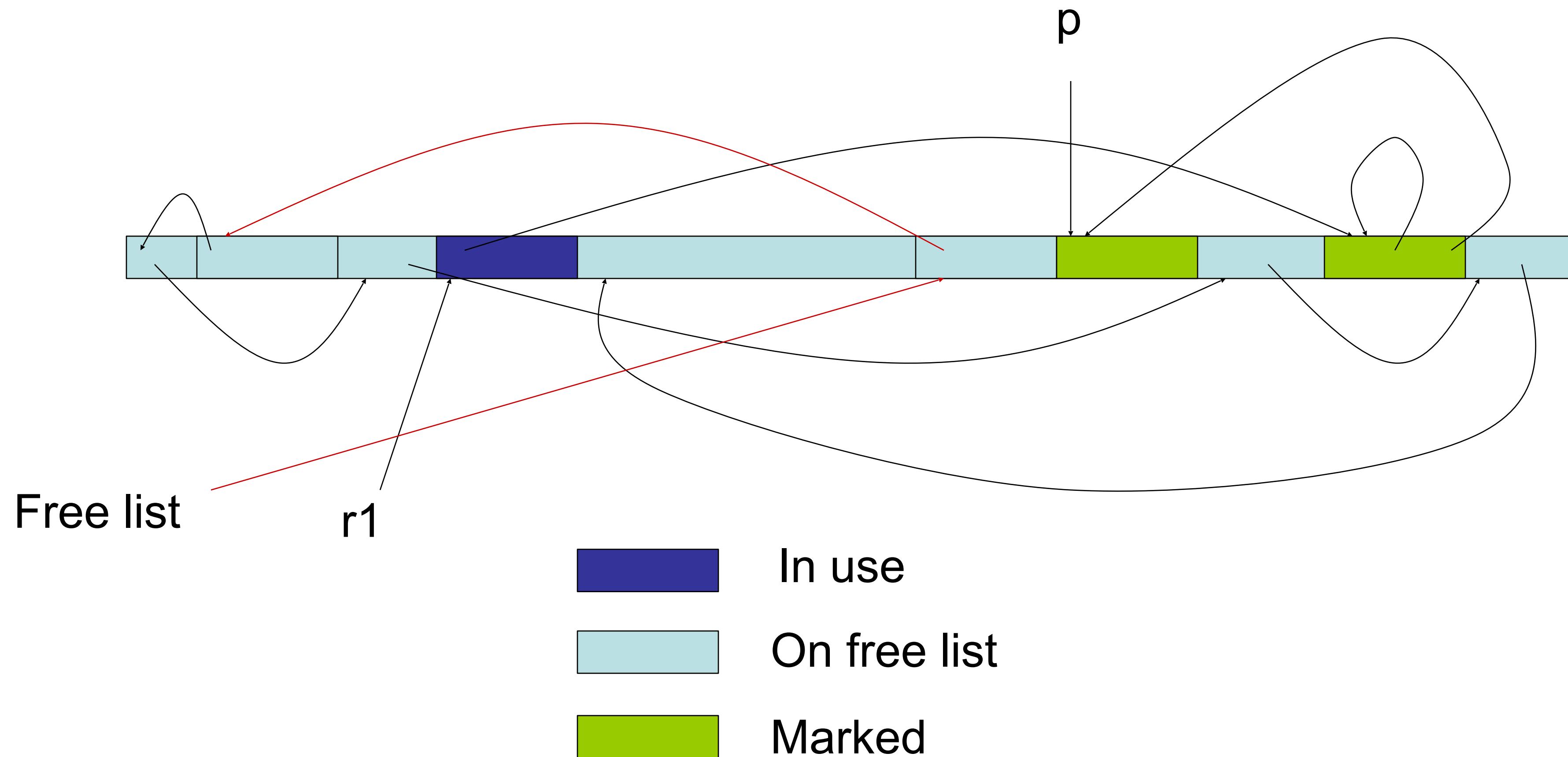
Example

Sweep Phase



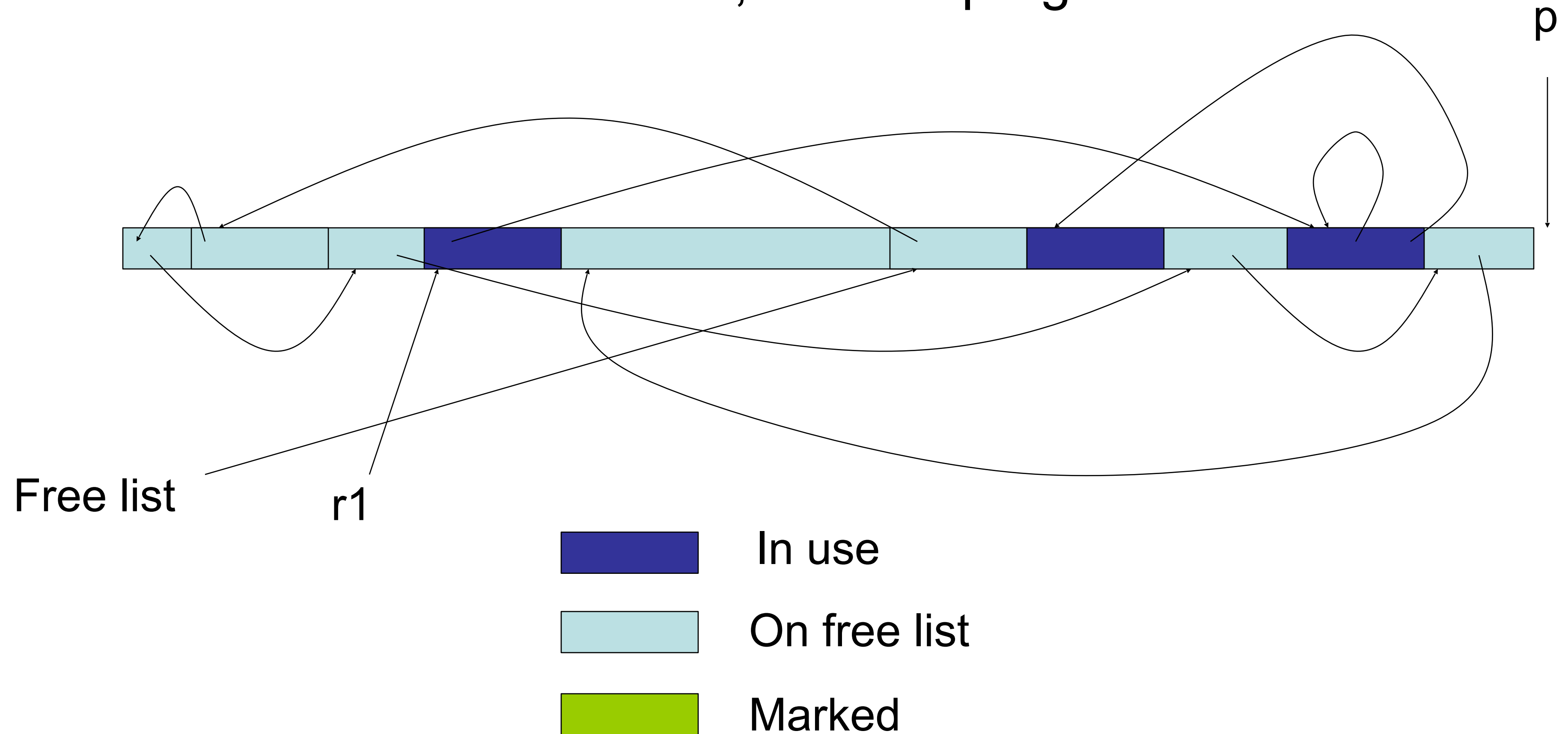
Example

Sweep Phase



Example

Sweep Phase: GC complete when heap boundary encountered; resume program



Cost of Mark Sweep

- Cost of mark phase:
 - $O(R)$ where R is the # of reachable words
 - Assume cost is $c1 * R$ ($c1$ may be 10 instr's)
- Cost of sweep phase:
 - $O(H)$ where H is the # of words in entire heap
 - Assume cost is $c2 * H$ ($c2$ may be 3 instr's)
- Analysis
 - Each collection returns $H - R$ words
 - For every allocated word, we have GC cost:
 - $((c1 * R) + (c2 * H)) / (H - R)$
 - R / H must be sufficiently small or GC cost is high
 - Eg: if R / H is larger than .5, increase heap size
 - Mark-sweep requires extra space like copying collection

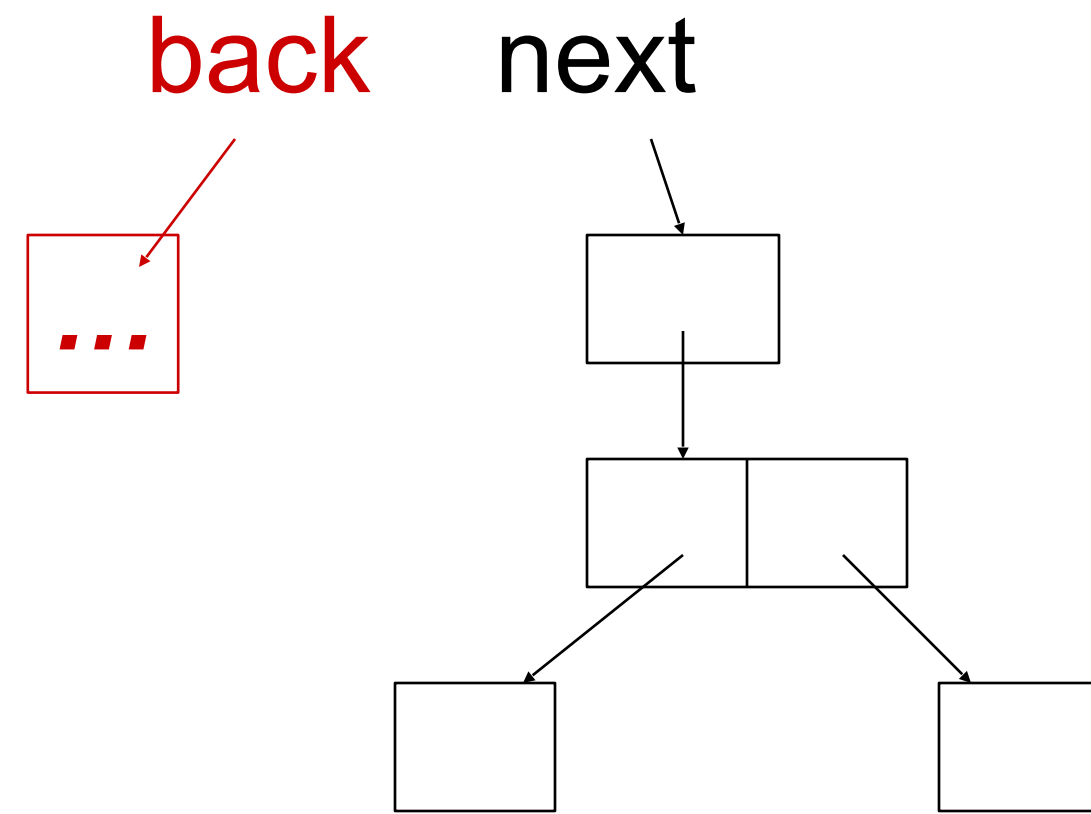
A Hidden Cost

- Depth-first search is usually implemented as a recursive algorithm
 - Uses stack space proportional to the longest path in the graph of reachable objects
 - one activation record/node in the path
 - activation records are big
 - If the heap is one long linked list, the stack space used in the algorithm will be greater than the heap size!!
 - What do we do?

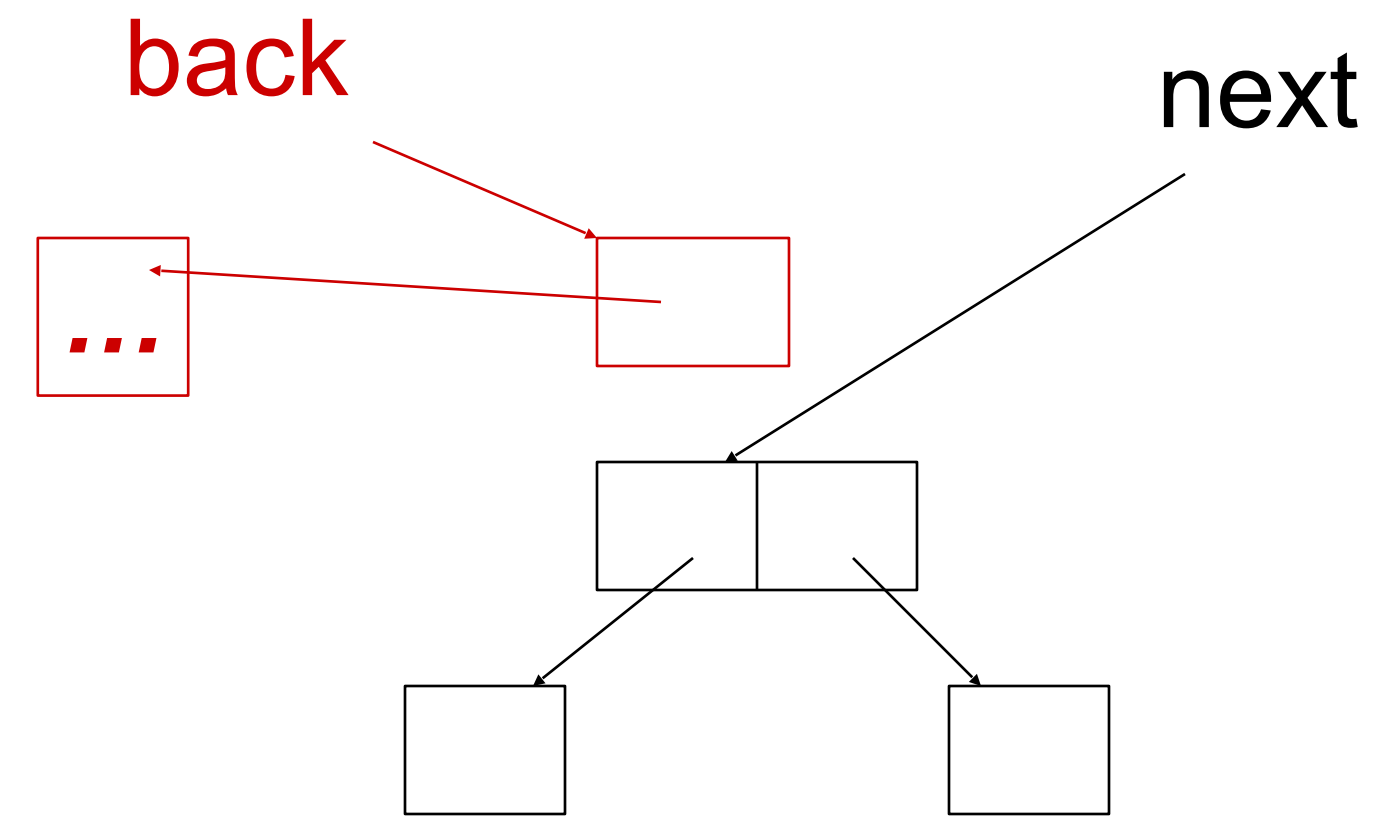
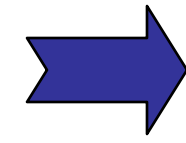
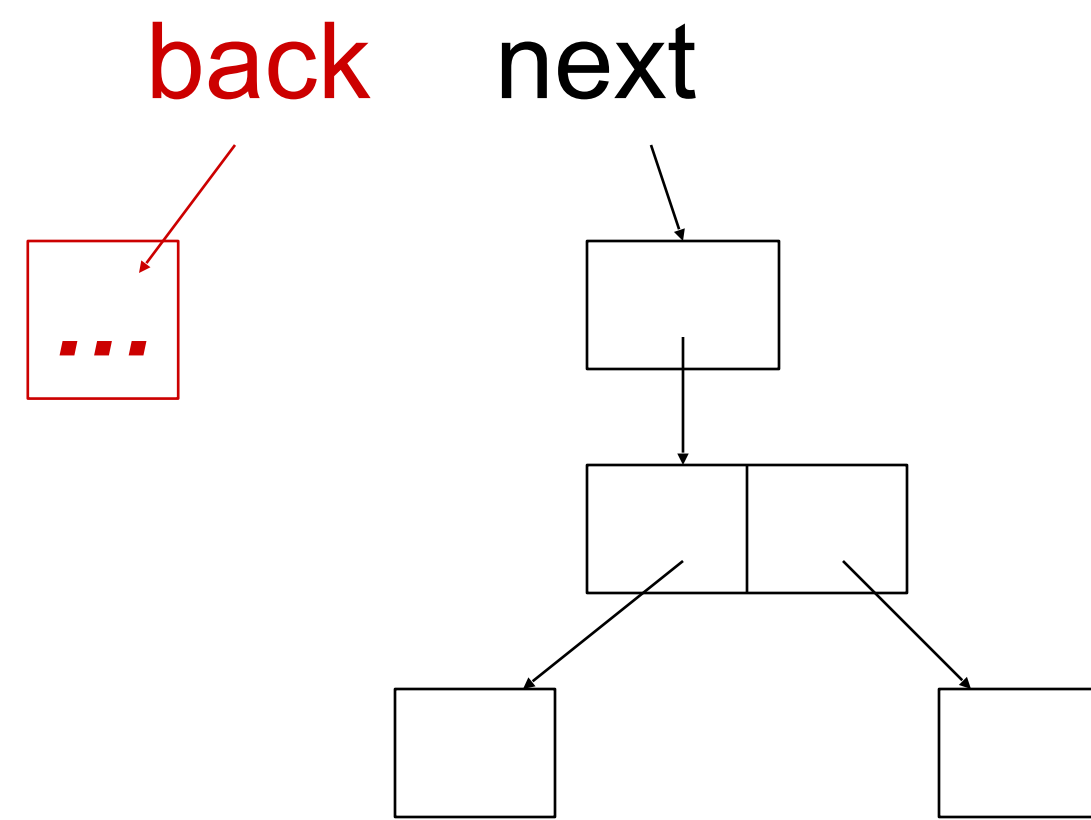
A nifty trick

- Deutsch-Schorr-Waite pointer reversal
 - Rather using a recursive algorithm, reuse the components of the graph you are traversing to build an explicit stack
 - This implementation trick only demands a few extra bits/block rather than an entire activation record/block
 - We already needed a few extra bits per block to hold the “mark” anyway

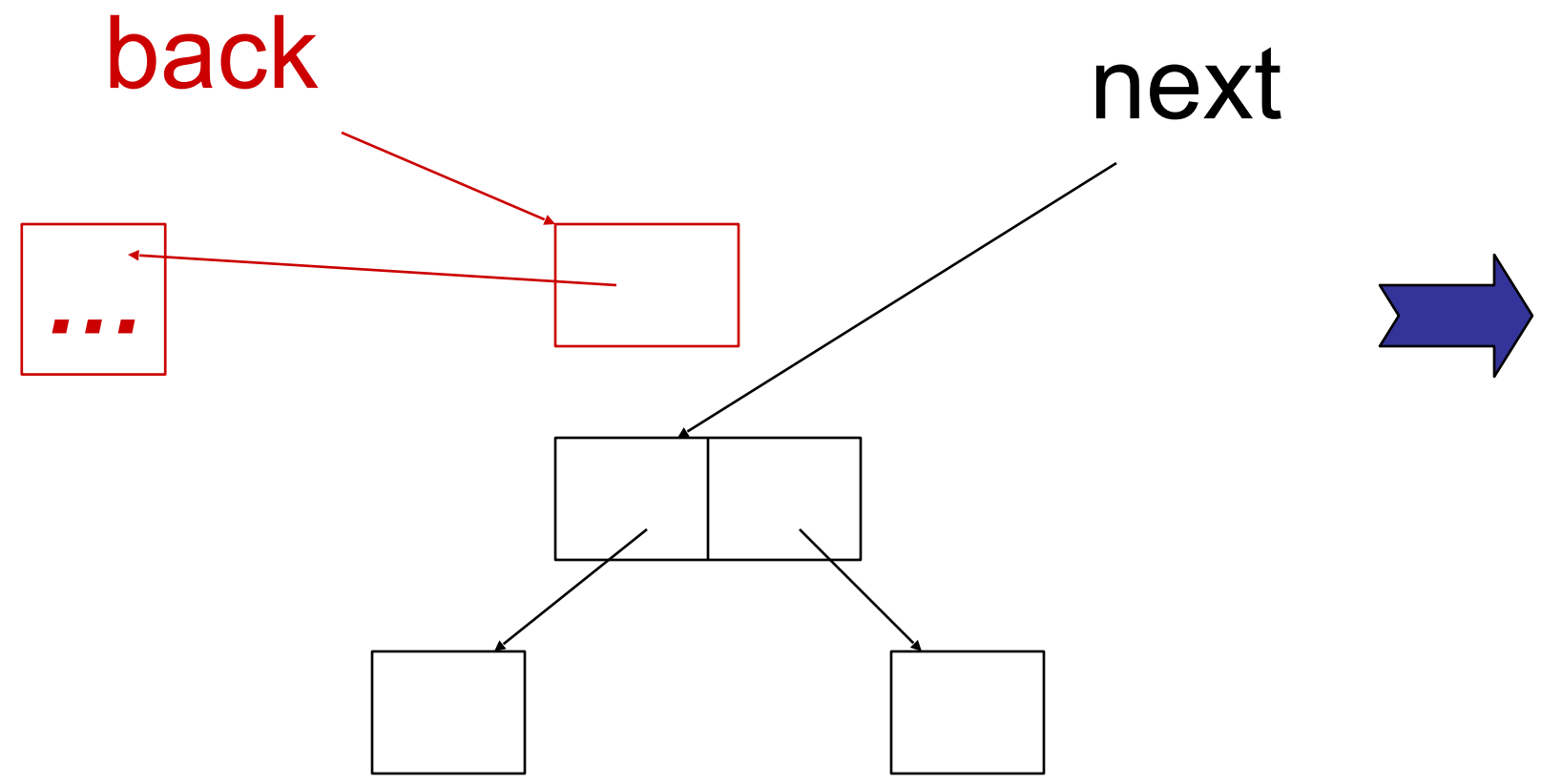
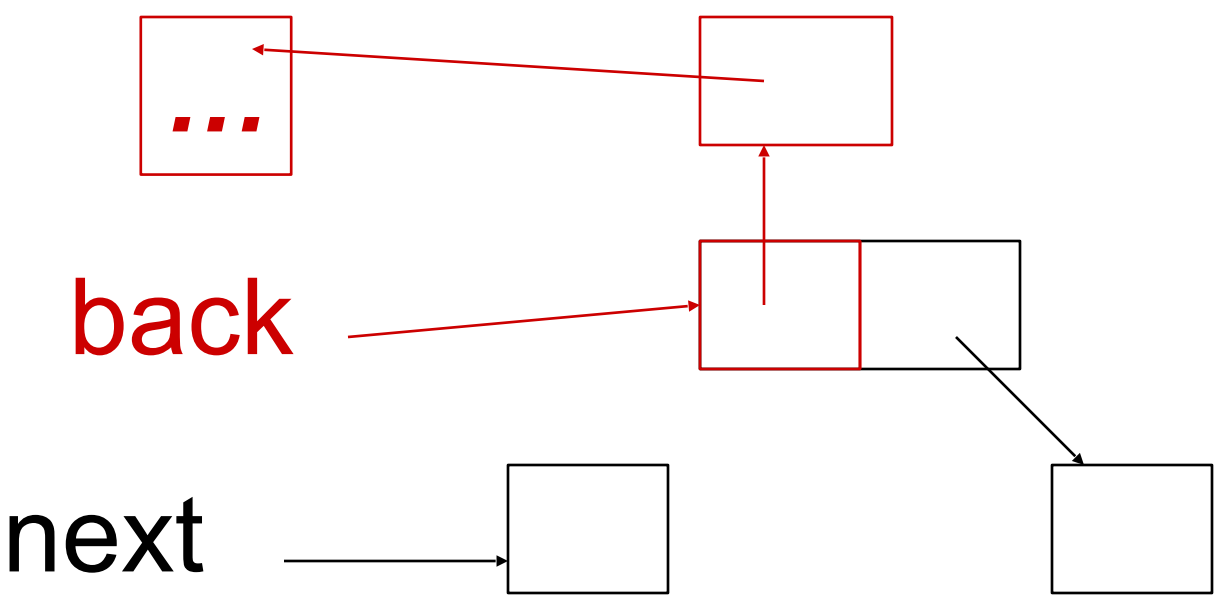
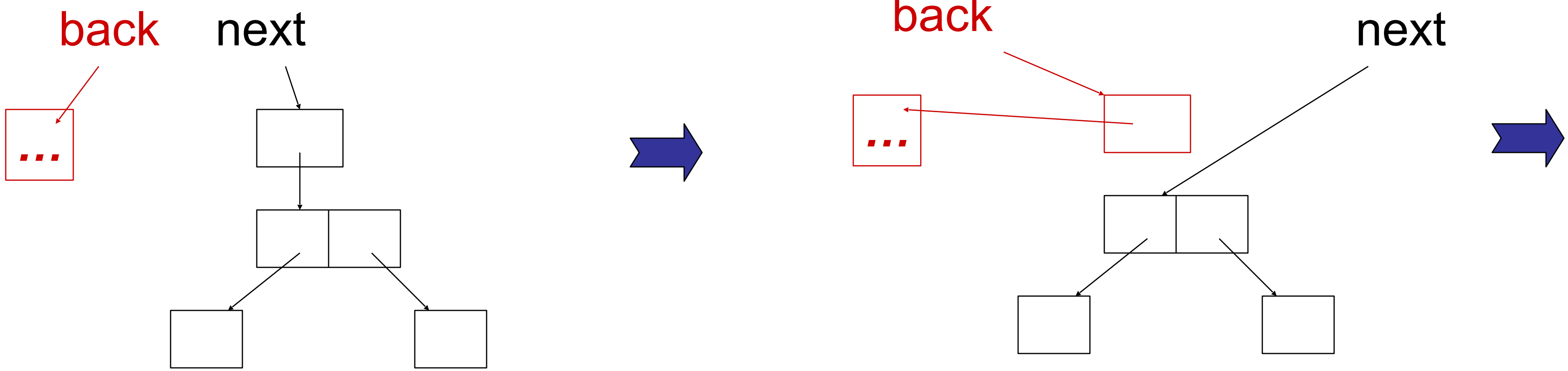
DSW Algorithm



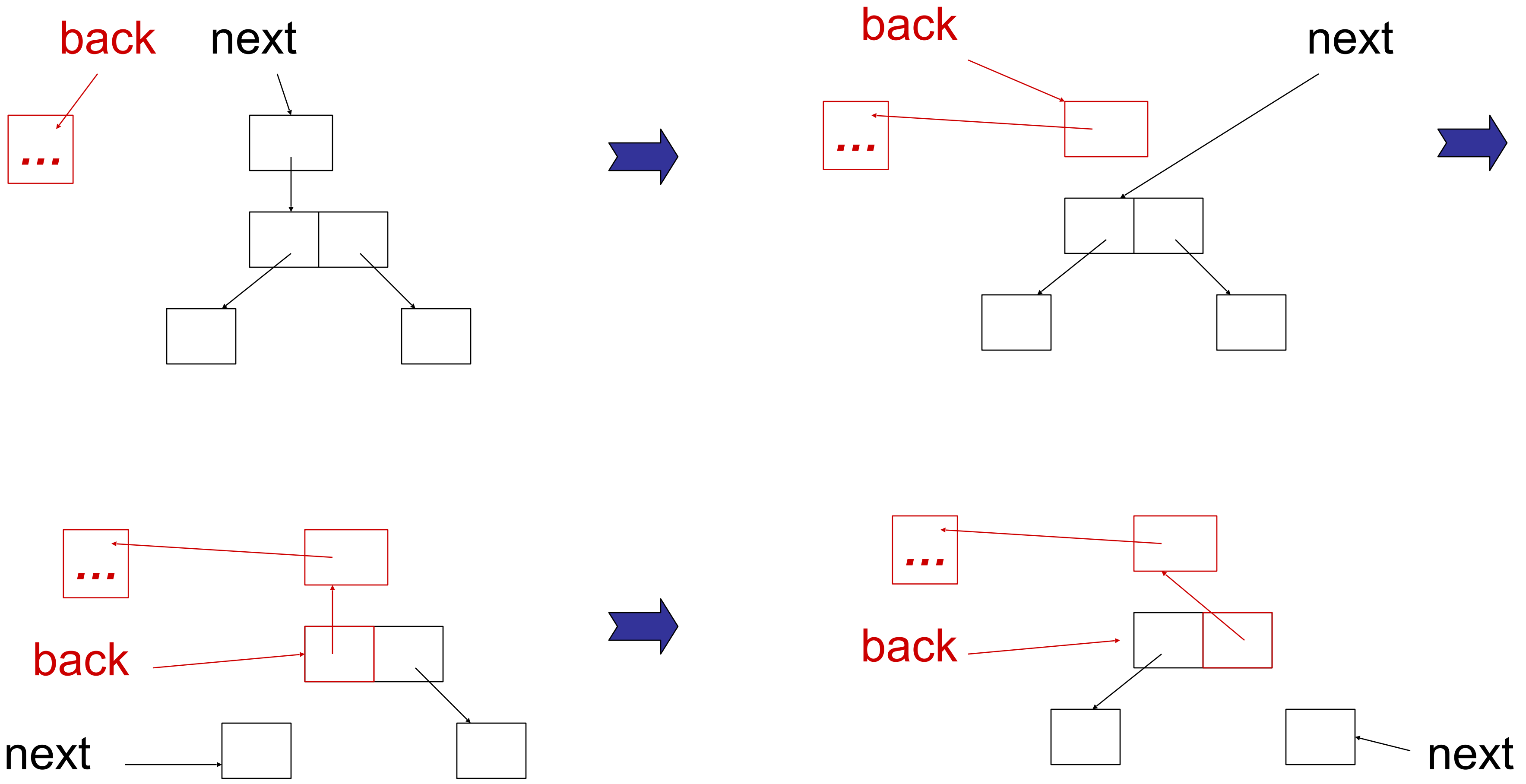
DSW Algorithm



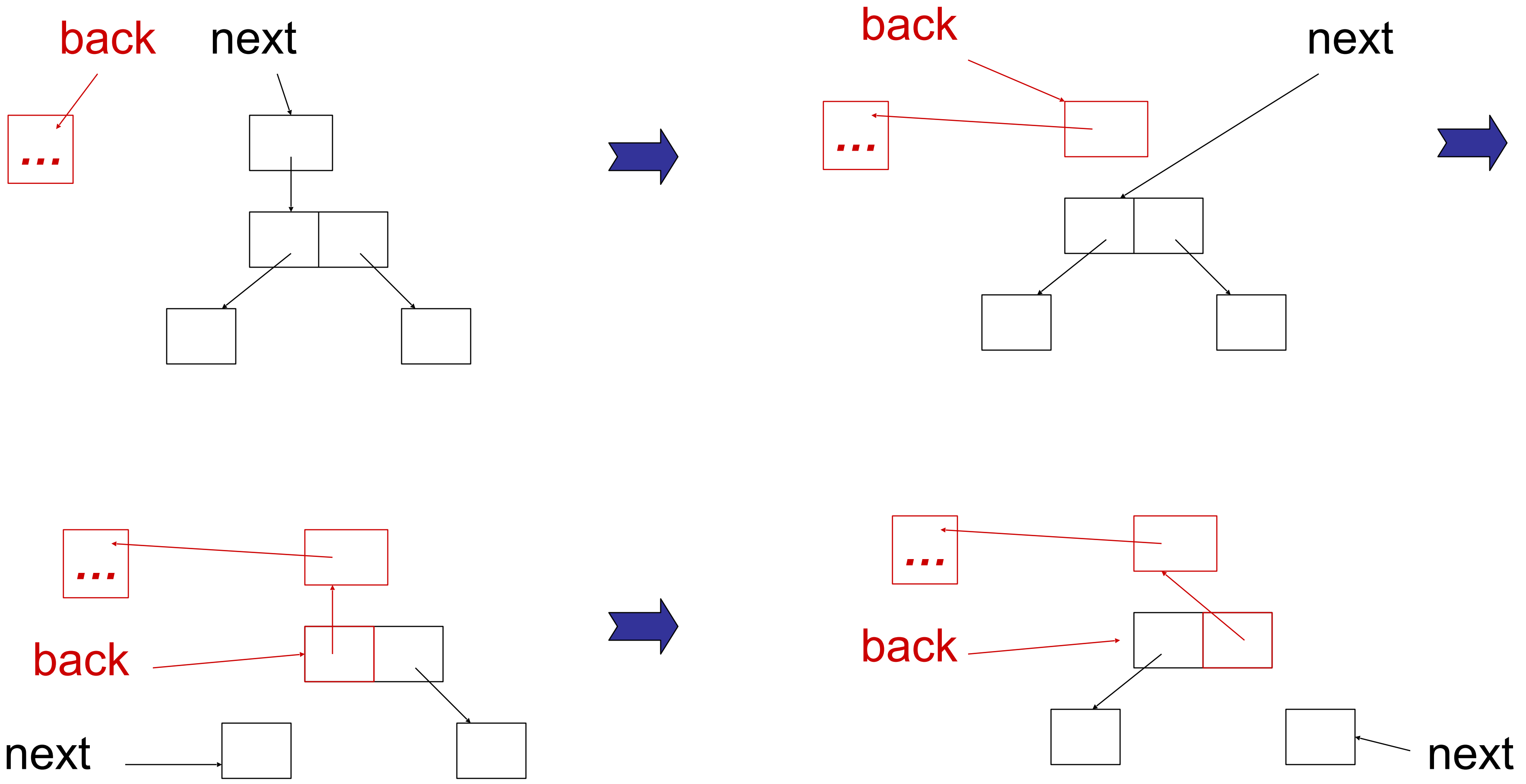
DSW Algorithm



DSW Algorithm



DSW Algorithm



- extra bits needed to keep track of which record fields we have processed so far

DSW Setup

- Extra space required for sweep:
 - 1 bit/record to keep track of whether the record has been seen (the “mark bit”)
 - $f \log 2$ bits/record where f is the number of fields in the record to keep track of how many fields have been processed
 - assume a field of each record x : $x.done$
- Functions:
 - `mark x` = sets x 's mark bit
 - `marked x` = true if x 's mark bit is set
 - `pointer x` = true if x is a pointer
 - `fields x` = returns number of fields in the record x

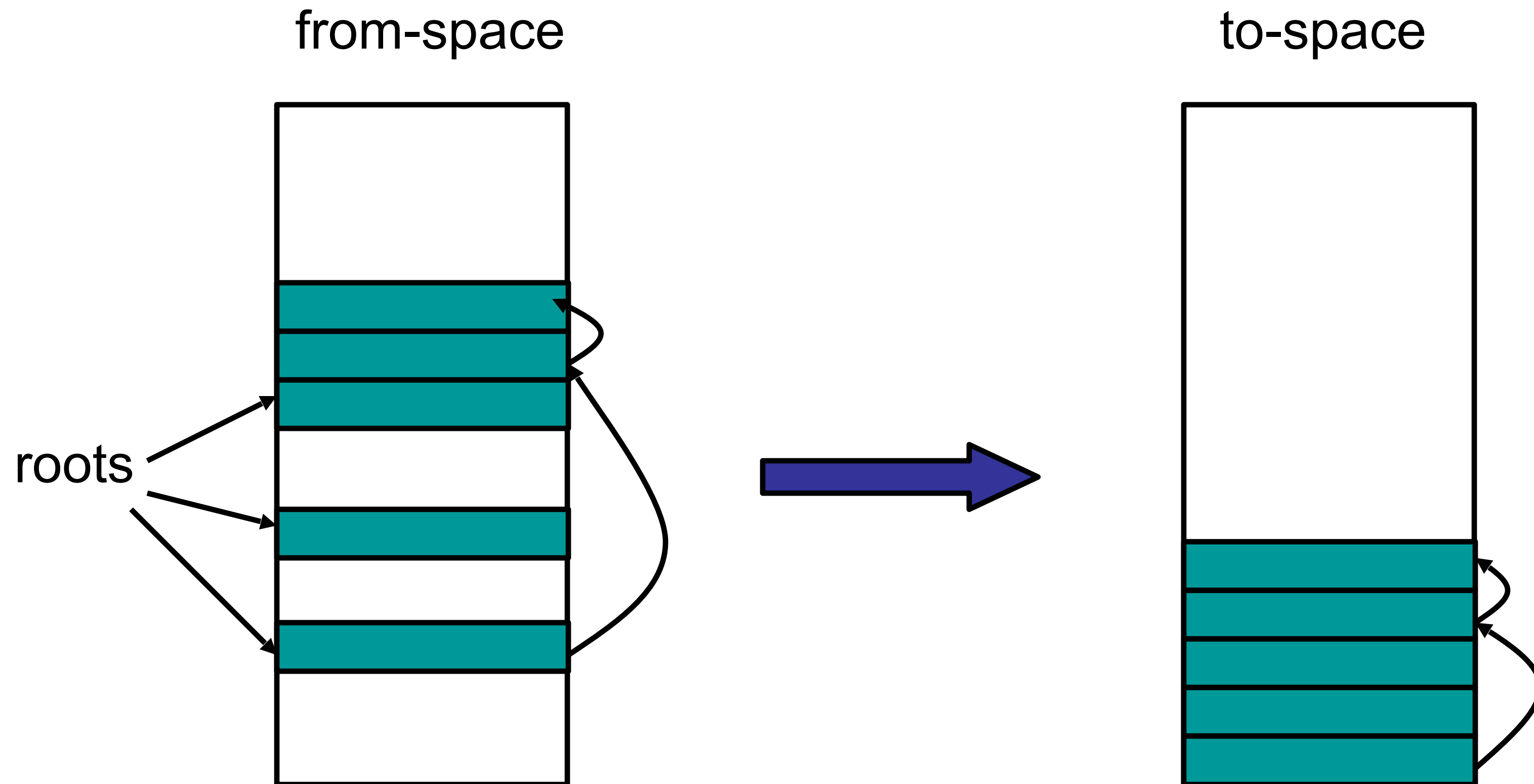
More Mark-Sweep

- Mark-sweep collectors can benefit from the tricks used to implement malloc/free efficiently
 - multiple free lists, one size of block/list
- Mark-sweep can suffer from fragmentation
 - blocks not copied and compacted like in copying collection
- Mark-sweep maximum space usage is the total heap size
 - but if the ratio of live data to heap size is too large then performance suffers

Copying Collection

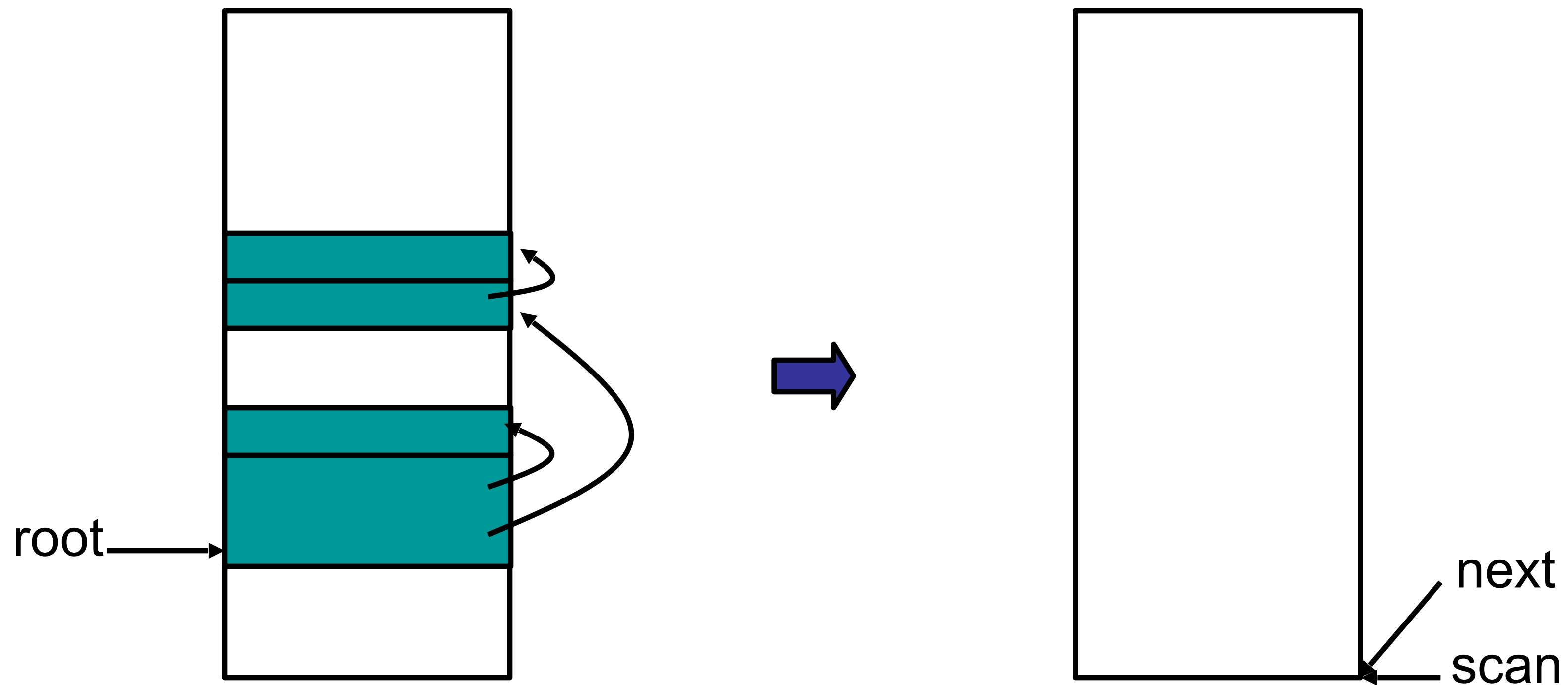
- Basic idea: use 2 heaps
 - One used by program
 - The other unused until GC time
- GC:
 - Start at the roots & traverse the reachable data
 - Copy reachable data from the active heap (from-space) to the other heap (to-space)
 - Dead objects are left behind in from space
 - Heaps switch roles

Copying Collection



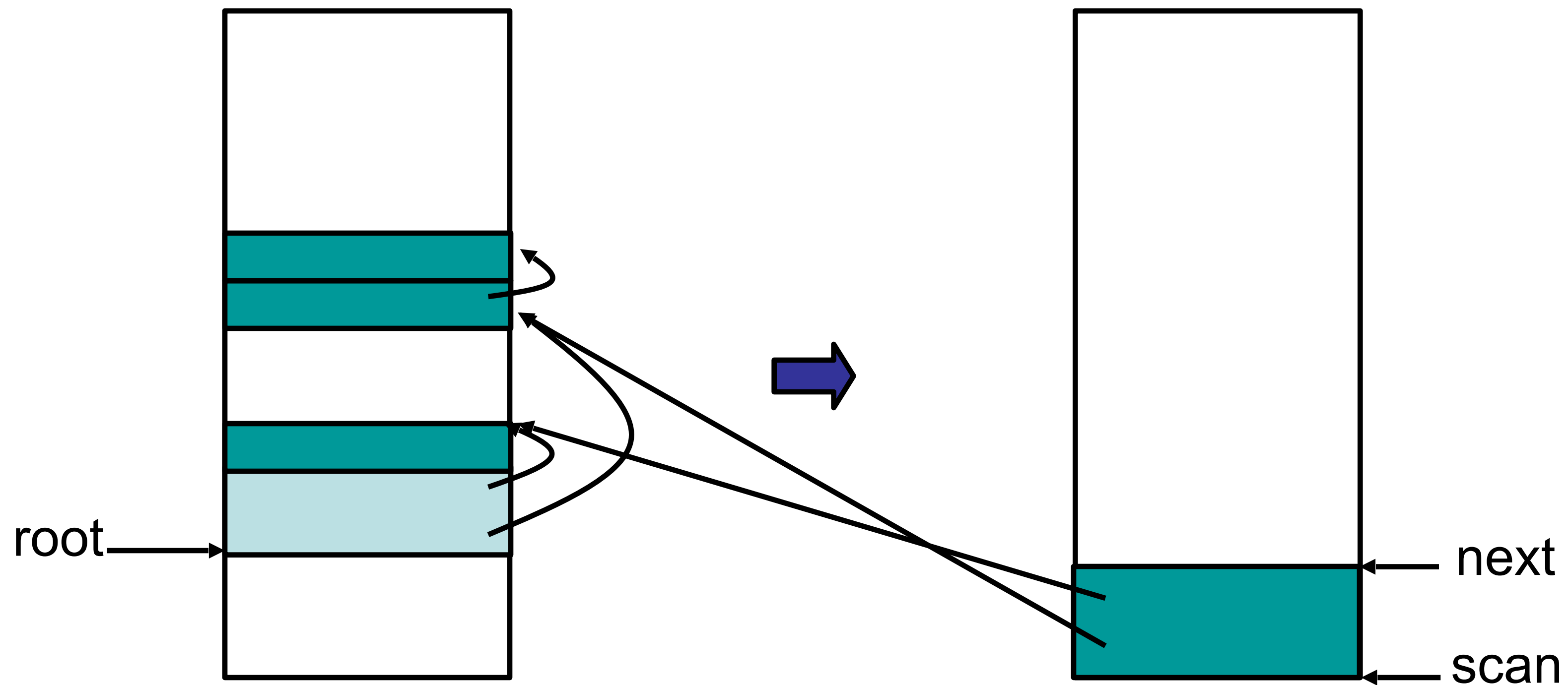
Copying GC

- Cheny's algorithm for copying collection
 - Traverse data breadth first, copying objects from from-space to to-space



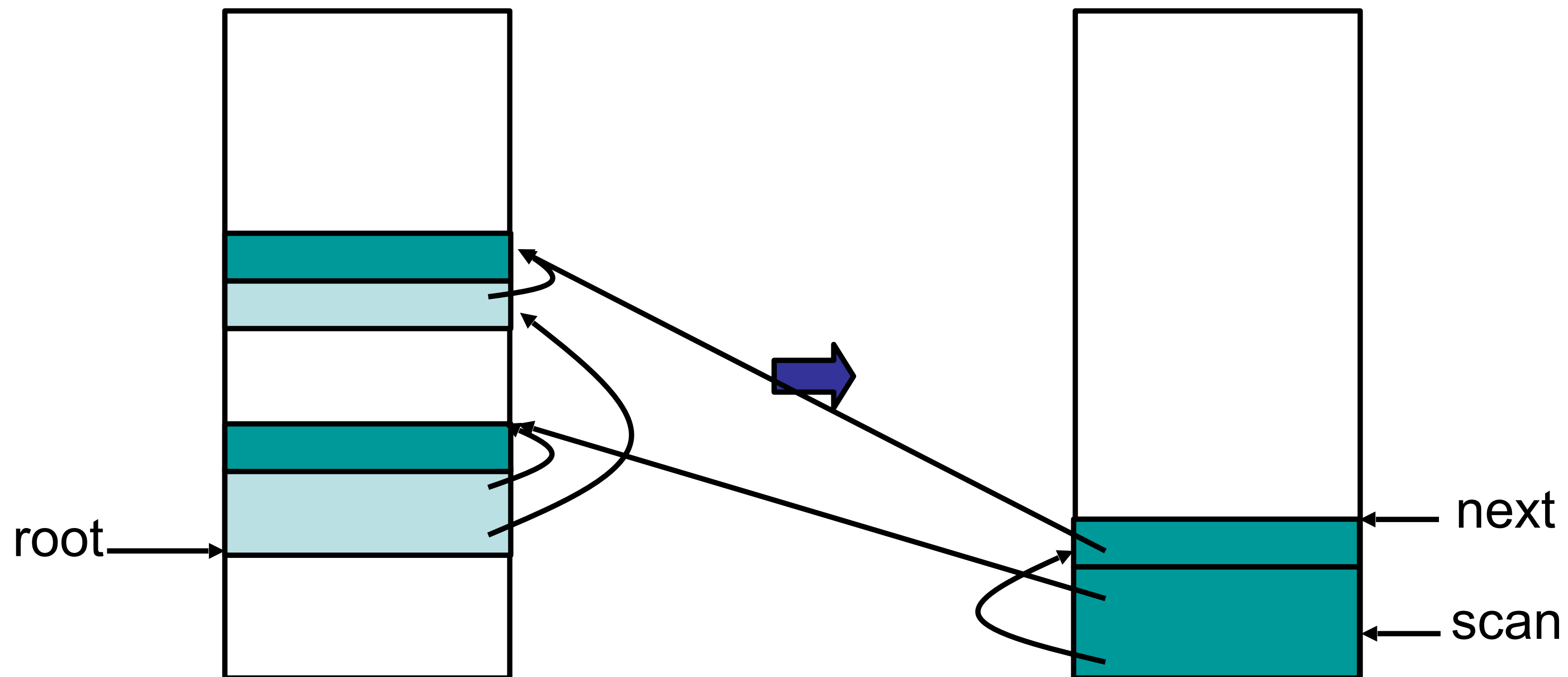
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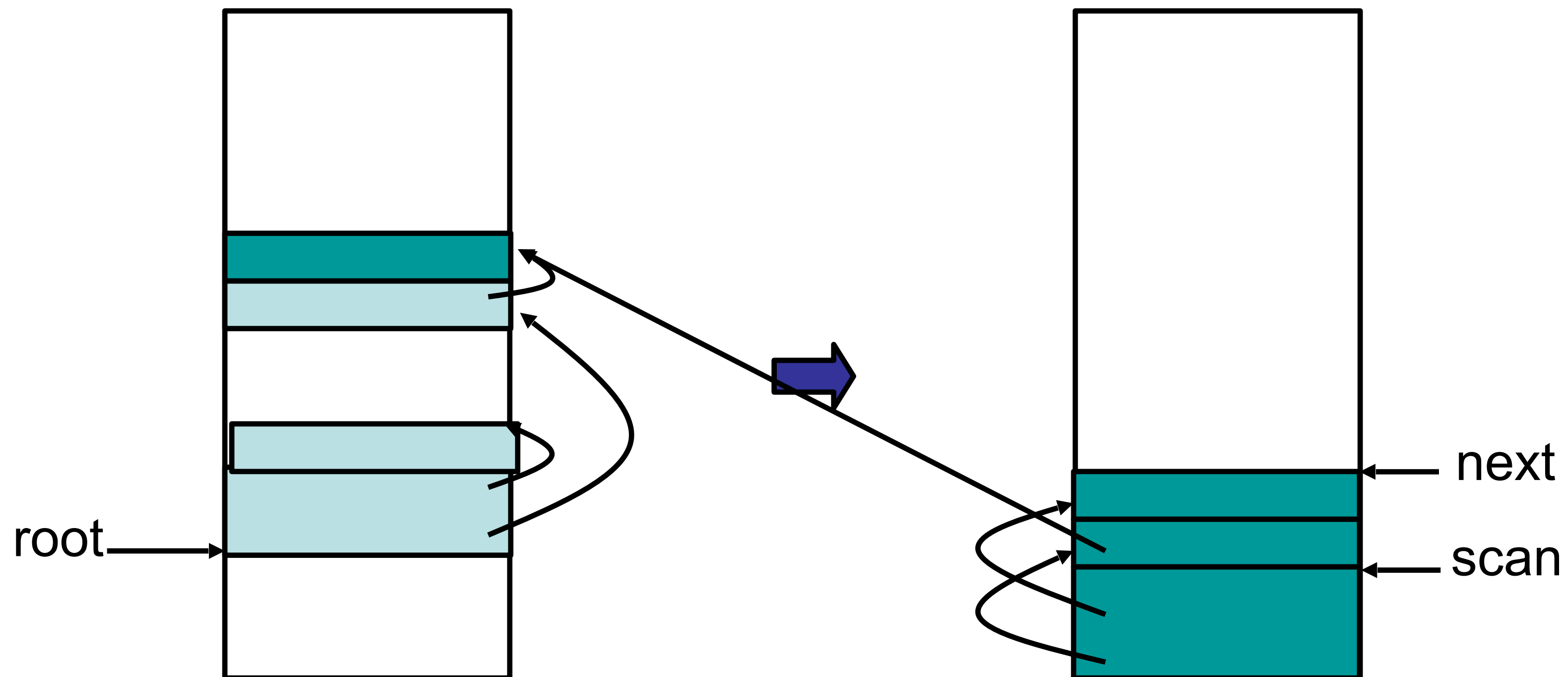
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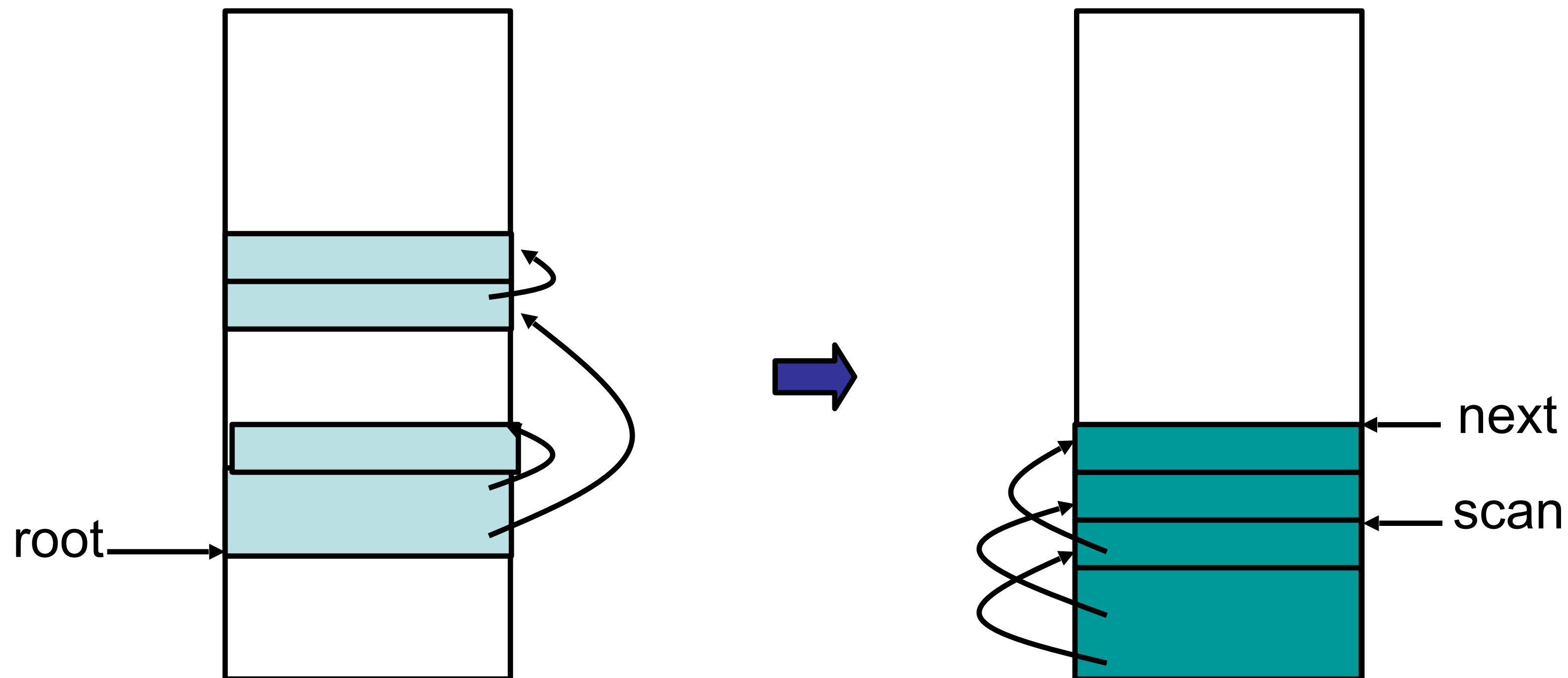
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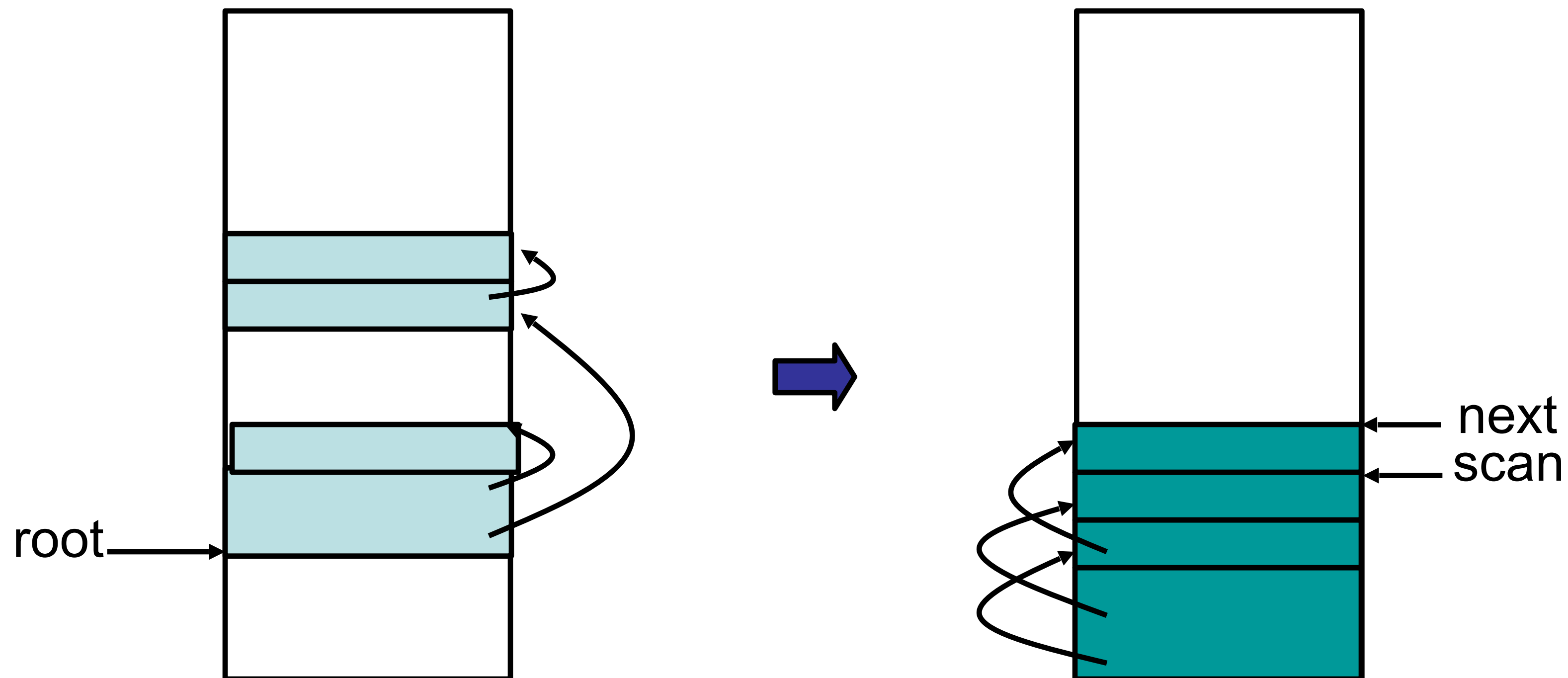
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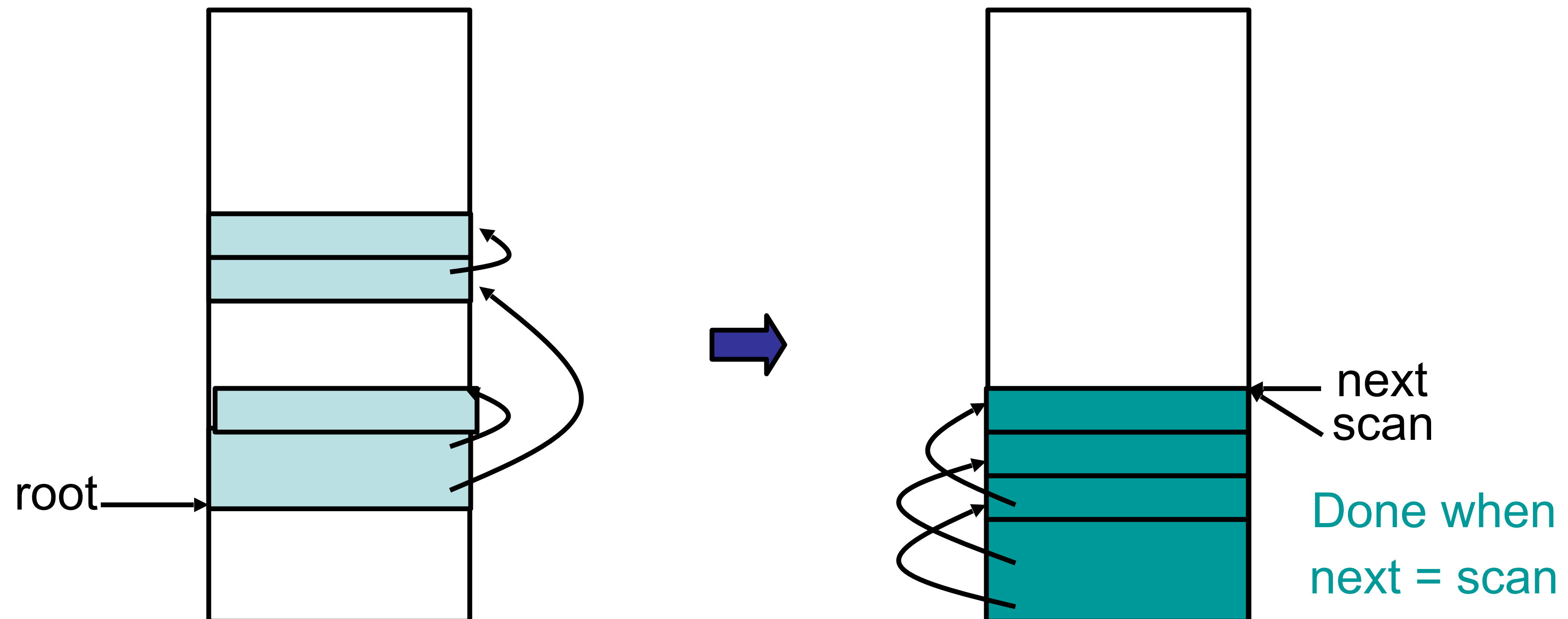
Copying GC

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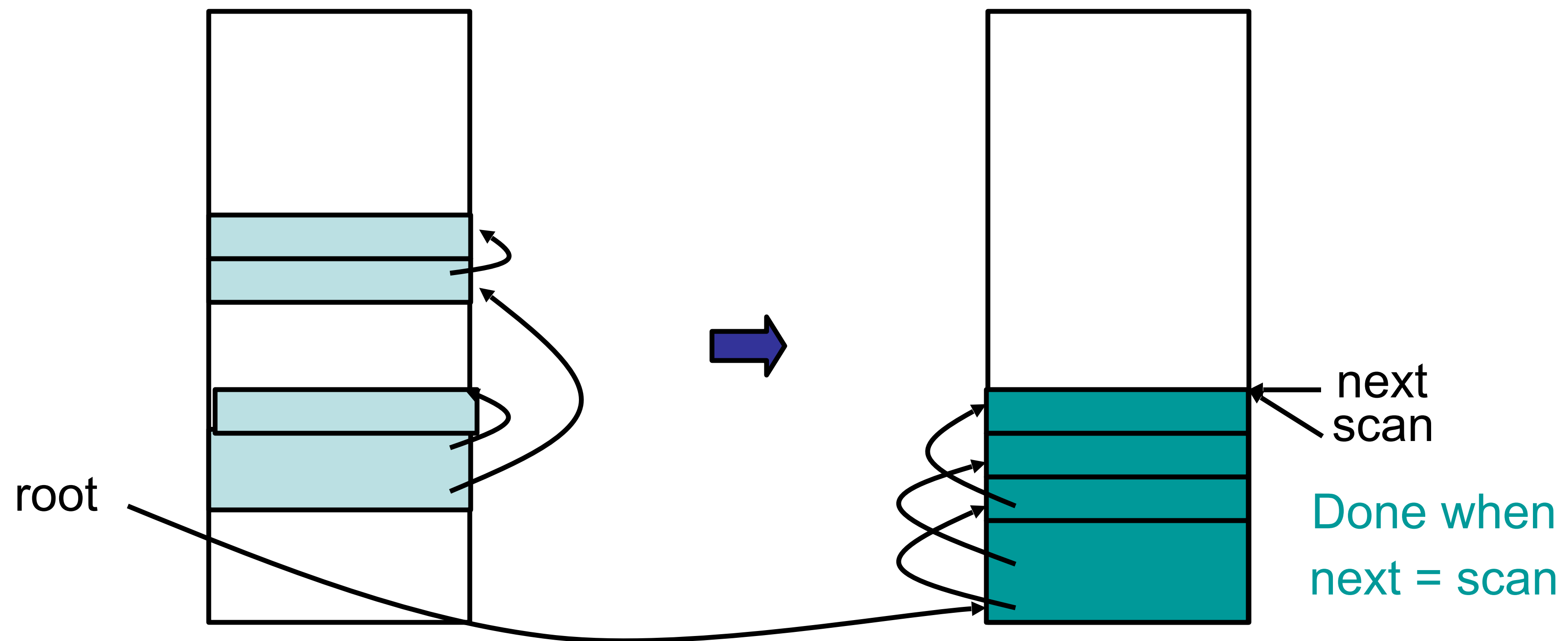
Copying GC

- Cheny's algorithm for copying collection
 - Traverse data breadth first, copying objects from from-space to to-space



Copying GC

- Cheny's algorithm for copying collection
 - Traverse data breadth first, copying objects from from-space to to-space



Copying GC

- Pros
 - Simple & collects cycles
 - Run-time proportional to # live objects
 - Automatic compaction eliminates fragmentation
 - Fast allocation: pointer increment by object size
- Cons
 - Precise type information required (pointer or not)
 - Tag bits take extra space; normally use header word
 - Twice as much memory used as program requires
 - Usually, we anticipate live data will only be a small fragment of store
 - Allocate until 70% full
 - From-space = 70% heap; to-space = 30%
 - Long GC pauses = bad for interactive, real-time apps

Generational GC

- **Empirical observation:** if an object has been reachable for a long time, it is likely to remain so
- **Empirical observation:** in many languages (especially functional languages), most objects died young
- **Conclusion:** we save work by scanning the young objects frequently and the old objects infrequently

Generational GC

- Assign objects to different generations G0, G1, ...
 - G0 contains young objects, most likely to be garbage
 - G0 scanned more often than G1
 - Common case is two generations (new, tenured)
 - Roots for GC of G0 include all objects in G1 in addition to stack, registers

Generational GC

- How do we avoid scanning tenured objects?
 - Observation: old objects rarely point to new objects
 - Normally, object is created and when it initialized it will point to older objects, not newer ones
 - Only happens if old object modified well after it is created
 - In functional languages that use mutation infrequently, pointers from old to new are very uncommon
 - Compiler inserts extra code on object field pointer write to catch modifications to old objects
 - Remembered set is used to keep track of objects that point into younger generation. Remembered set included in set of roots for scanning.

Generational GC

- Other issues
 - When do we **promote** objects from young generation to old generation
 - Usually after an object survives a collection, it will be promoted
 - How big should the generations be?
 - Appel says each should be exponentially larger than the last
 - When do we collect the old generation?
 - After several **minor collections**, we do a **major collection**

Generational GC

- Other issues
 - Sometimes different GC algorithms are used for the new and older generations.
 - Why? Because they have different characteristics
 - Copying collection for the new
 - Less than 10% of the new data is usually live
 - Copying collection cost is proportional to the live data
 - Mark-sweep for the old

Conservative Collection

- Even languages like C can benefit from GC
 - Boehm-Weiser-Demers **conservative GC** uses heuristics to determine which objects are pointers and which are integers without any language support
 - last 2 bits are non-zero => can't be a pointer
 - integer is not in allocated heap range => can't be a pointer
 - mark phase traverses all possible pointers
 - conservative because it may retain data that isn't reachable
 - thinks an integer is actually a pointer
 - since it does not copy objects (thereby changing pointer values), mistaking integers for pointers does not hurt
 - all gc is conservative anyway so this is almost never an issue (despite what people say)
 - sound if your program doesn't manufacture pointers from integers by, say, using xor (using normal pointer arithmetic is fine)

Compiler Interface

- The interface to the garbage collector involves two main parts
 - allocation code
 - languages can allocate up to approx 1 word/7 instructions
 - allocation code must be **blazingly** fast!
 - should be inlined and optimized to avoid call-return overhead
 - gc code
 - to call gc code, the program must identify the roots
 - to traverse data, heap layout must be specified somehow

Allocation Code

Assume size of record allocated is N :

1. Call alloc code
2. Test $\text{next} + N < \text{limit}$ (call gc on failure)
3. Move next into function result
4. Clear $M[\text{next}], \dots, M[\text{next} + N - 1]$
5. $\text{next} = \text{next} + N$
6. Return from alloc code

Allocation Code

Assume size of record allocated is N:

1. Call alloc function
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5. $\text{next} = \text{next} + N$
6. Return from alloc function
7. Move result into computationally useful place
8. Store useful values into $M[\text{next}], \dots, M[\text{next} + N - 1]$

useful computation
not alloc overhead



Allocation Code

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inline
alloc
code

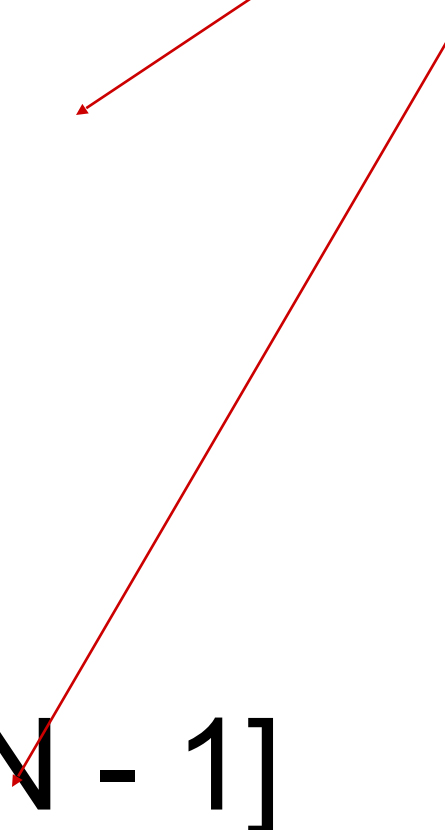


Allocation Code

Assume size of record allocated is N:

1. Call alloc function
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3. Move next **into computationally useful place**
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5. $\text{next} = \text{next} + N$
6. Return from alloc function
7. Move next into computationally useful place
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combine
moves



Allocation Code

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eliminate
useless
store



Allocation Code

Assume size of record allocated is N :

1. Call alloc function
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8. Store useful values into $M[\text{next}], \dots, M[\text{next} + N - 1]$

total overhead for allocation on the order of 3 instructions/alloc

Calling GC code

- To call the GC, program must:
 - identify the **roots**:
 - a **GC-point**, is an control-flow point where the garbage collector may be called
 - allocation point; function call
 - for any GC-point, compiler generates a **pointer map** that says which registers, stack locations in the current frame contain pointers
 - a global table maps GC-points (code addresses) to pointer maps
 - when program calls the GC, to find all roots:
 - GC scans down stack, one activation record at a time, looking up the current pointer map for that record

Calling GC code

- To call the GC, program must:
 - enable GC to determine **data layout** of all objects in the heap
 - every record has a header with size and pointer info
 - in object oriented languages like Java:
 - each object has an extra field that points to class definition
 - gc uses class definition to determine object layout including size and pointer info

Summary

- Garbage collectors are a complex and fascinating part of any modern language implementation
- Different collection algs have pros/cons
 - explicit MM, reference counting, copying, generational, mark-sweep
 - all methods, including explicit MM have costs
 - optimizations make allocation fast, GC time, space and latency requirements acceptable
 - additional reading: Appel Chapter 13