



EECS 483: Compiler Construction

Lecture 7:

Loops, Mutable Variables

February 5, 2025

Extending the Snake Language



What source-level programming features would allow us to express cyclic control-flow graphs?

1. Functional: recursive functions, tail calls
- 2. Imperative: loops, mutable variables**

We'll look at these each in turn and study how to compile them to SSA.

Imperative Snake Language



Imperative Snake Language "Imp"

- Mutable variables
- statement-expression distinction
- while loops
- return/break/continue

```
var m = 100;  
var n = 25;  
while !(m == n) {  
    if m < n {  
        n := n - m  
    } else {  
        m := m - n  
    }  
};  
return m
```

Imperative Snake Language

concrete syntax



<block>:

- | **<statement>**
- | **<statement>** ; **<statement>**

<statement>:

- | **var** **IDENTIFIER** = **<expr>**
- | **IDENTIFIER** := **<expr>**
- | **if** **<expr>** { **<block>** }
- | **if** **<expr>** { **<block>** } **else** { **<block>** }
- | **while** **<expr>** { **<block>** }
- | **continue**
- | **break**
- | **return** **<expr>**

<expr>:

- | **IDENTIFIER**
- | **NUMBER**
- | **true**
- | **false**
- | **!** **<expr>**
- | **<prim1>** (**<expr>**)
- | **<expr>** **<prim2>** **<expr>**
- | (**<expr>**)

Imperative Snake Language

abstract syntax

```
pub enum Block {  
    End(Box<Statement>),  
    Sequence(Box<Statement>, Box<Block>),  
}
```

```
pub enum Statement {  
    VarDecl(String, Expression),  
    VarUpdate(String, Expression),  
    If(Expression, Block, Block),  
    IfElse(Expression, Block, Block),  
    While(Expression, Block),  
    Continue,  
    Break,  
    Return(Expression),  
}
```

```
pub enum Expression {  
    Var(String),  
    Num(i64),  
    Bool(bool),  
    Prim(Prim, Vec<Expression>),  
}
```



Imperative Snake Language

well-formedness

Still have a notion of scope, shadowing:

1. Check variables are declared before use
2. Shadowing is allowed, semantically shadowed var is a **different** mutable variable

Translate away shadowing to unique variable names to avoid headaches, as usual



Imperative Snake Language

well-formedness



```
var x = y + z;  
return x
```

undeclared var y, z

similar to existing scope checker

Imperative Snake Language

well-formedness

If implementing a procedure that returns a value, need to ensure that every code path ends in a return

```
...  
if b {  
    ...  
    return x;  
} else {  
    x := 5  
}
```



Imperative Snake Language

well-formedness

Naked break/continue:

Verify that break/continue operations only occur inside of an enclosing while loop

```
while x != 0 {  
    x := x - 1  
    if y > 10 {  
        continue  
    }  
    ...  
}  
continue
```



Imperative Snake Language

semantics

Each variable acts like a 64-bit "register"

When evaluating, need to keep track of the current state of all the variables

Imperative Snake Language

semantics



```
var x = 10;  
...  
if x != y {  
    var x = 14;  
    ...  
    x := x + 1  
}  
return x;
```

shadowed variables should not be overwritten. Making variable names unique makes this easier to get right

Imperative Snake Language

semantics

while loop:

- check the condition expression

- true: execute the block and repeat

- false: execute the next statement

break:

- in a while loop, goto the next statement after the loop

continue:

- in a loop, goto the beginning of the loop

Imperative to SSA

Step 1: Expressions, variable declarations

Step 2: variable updates

Step 3: Join Points

Step 4: Loops

Step 5: Break, Continue, Return

Imperative to SSA

Step 1: Expressions, variable declarations

Expressions are defined just as in Adder: generate temporaries and use continuations to turn tree of operations into straightline code

Variable declarations are implemented just as with Let: a var declaration in Imp becomes a variable assignment in SSA

```
var x = 10;  
var p = (x * x) + 5 * x + 7;  
...
```

```
x = 10  
tmp0 = x * x  
tmp1 = 5 * x  
tmp2 = tmp0 + tmp2  
p = tmp2 + 7  
...
```

Imperative to SSA

Step 2: Variable Updates

```
var x = 10;  
x := (x * 2) + 1;  
x := x + x  
...
```

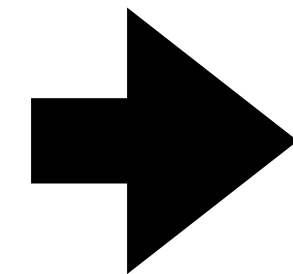
how to compile to SSA?

idea: the updated x acts like it's shadowing the original. Treat it as an assignment to a new variable

Imperative to SSA

Step 2: Variable Updates

```
var x = 10;  
x := (x * 2) + 1;  
x := x + x  
...
```



```
x0 = 10  
tmp0 = x0 * 2  
x1 = tmp0 + 1  
x2 = x1 + x1  
...
```

Keep track in an environment of the current "version" of each variable in scope

Imperative to SSA

Step 2: Variable Updates

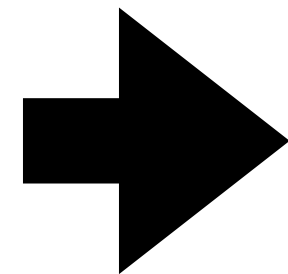
Simple idea: replace mutable updates with assignments to a new variable in straightline code, mutable variables are just shadowing!

Imperative to SSA

Step 2: If

Imperative to SSA

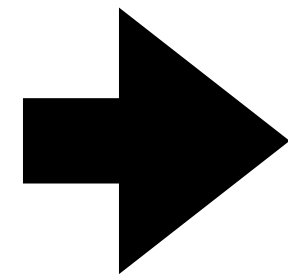
```
...  
var x = 10;  
if y {  
    x = x + 1  
} else {  
    x = x * 2  
    x = x - 1  
}  
return x
```



```
x0 = 10  
thn():  
    x1 = x0 + 1  
    br ??  
els():  
    x2 = x0 * 2  
    x3 = x2 - 1  
    br ??  
cbr y thn() els()
```

Imperative to SSA

```
...  
var x = 10;  
if y {  
    x = x + 1  
} else {  
    x = x * 2  
    x = x - 1  
}  
return x
```



Join points!

```
x0 = 10  
jn(x4):  
    ret x4  
thn():  
    x1 = x0 + 1  
    br jn(x1)  
els():  
    x2 = x0 * 2  
    x3 = x2 - 1  
    br jn(x3)  
cbr y thn() els()
```

Imperative to SSA

Step 2: If

Generate join points for if statements.

In an imperative program, join points are parameterized not just by a single variable, but by as many as can be updated in the two branches.

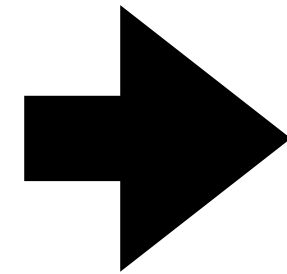
Need to calculate which variables to include in the join point:

Simplest algorithm is called **crude** ϕ -node insertion: add **every** variable that is in scope to the join point.

Rely on a later SSA-minimization pass to remove unnecessary parameters

Unnecessary Parameters

```
...  
var x = 10;  
var z = 7;  
if y {  
    x = x + 1  
} else {  
    y = x * 2  
    x = x - 1  
}  
var w = z * x  
return w + y
```



```
...  
x0 = 10  
z0 = 7  
jn(x4, y1, z1):  
    w = z1 * x4  
    tmp = w + y1  
    ret tmp  
thn():  
    x1 = x0 + 1  
    br jn(x1, y0, z0)  
els():  
    y2 = x0 * 2  
    x2 = x1 - 1  
    br jn(x2, y2, z0)  
cbr y0 thn() els()
```

Imperative to SSA

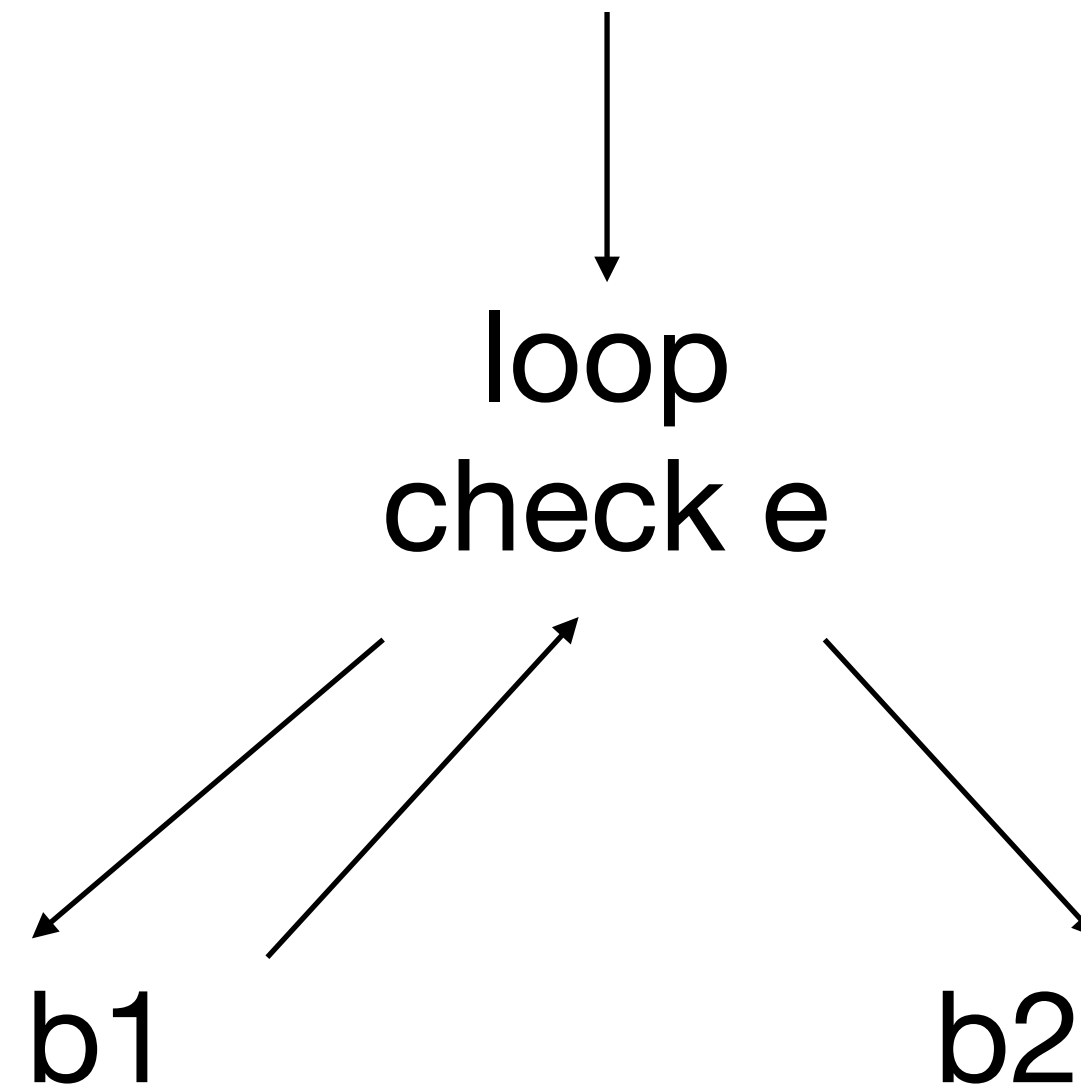
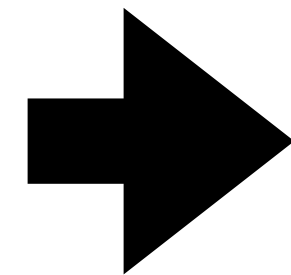
Step 4: while loops

encode semantics using SSA blocks

which blocks in a loop are join points?

Imperative to SSA

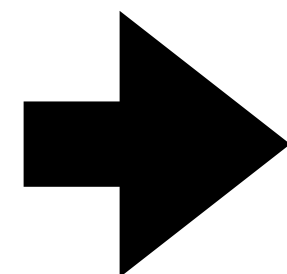
```
while e {  
    b1  
}  
b2
```



Notice: loop has 2 predecessors, so it is a join point, add block parameters

Imperative to SSA

```
while e {  
  b1  
}  
b2
```



```
loop(...): ;; loop is a join point, include all in-scope vars  
  done():  
    ... ;; compiled code for b2  
  body():  
    ... ;; compiled code for b1  
    br loop(...)  
  ...  
  c = ... ;; compiled code for e  
  cbr c body() done()  
br loop(...)
```

Imperative to SSA

Step 5: return, break, continue

Return is easy: just compile the expression and produce the ret terminator

Break, continue: depend on the **context**

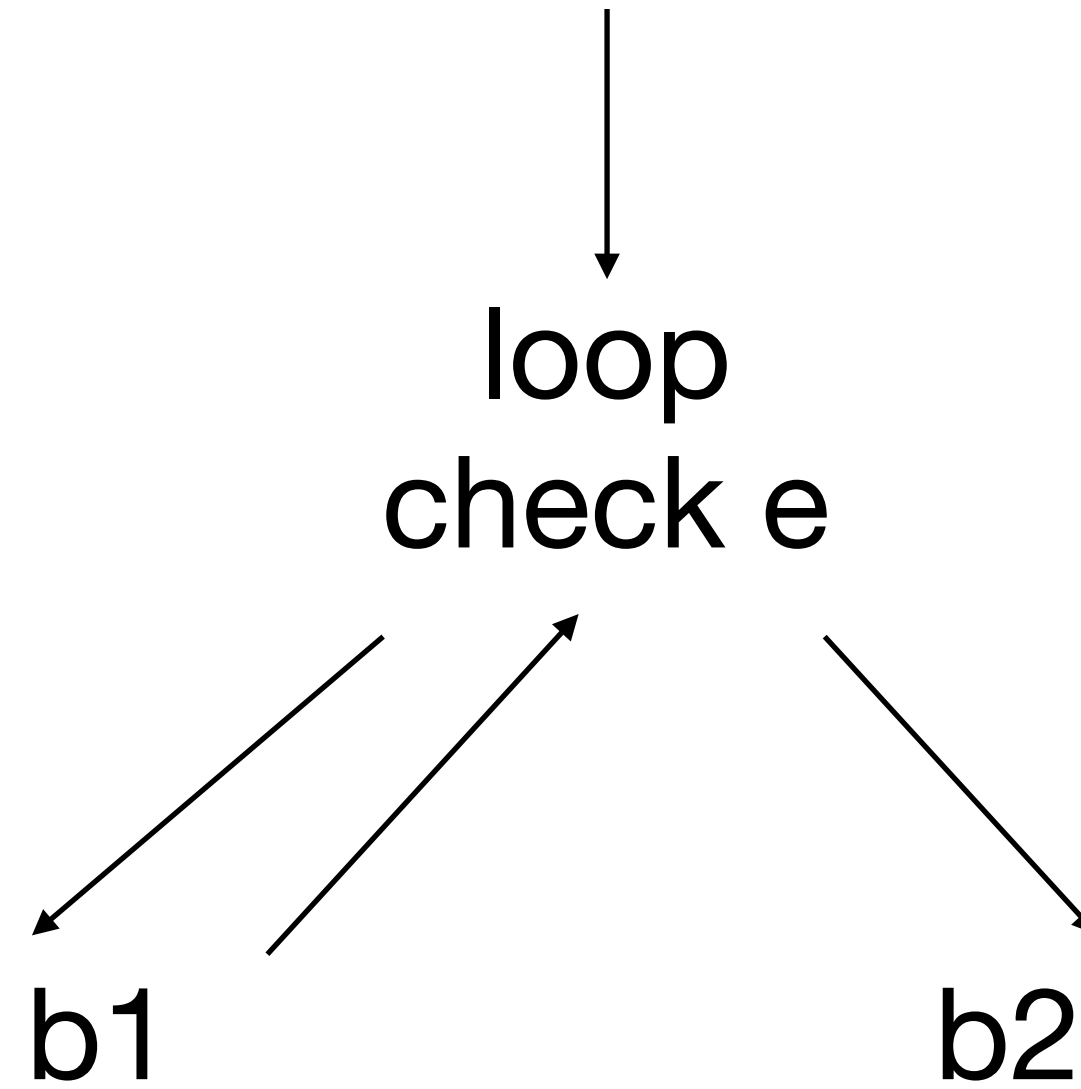
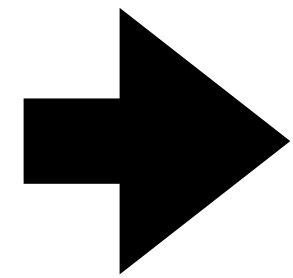
when we enter a while loop, we make blocks for the entry point and exit point

continue: branch to entry of loop

break: branch to exit of loop

Imperative to SSA

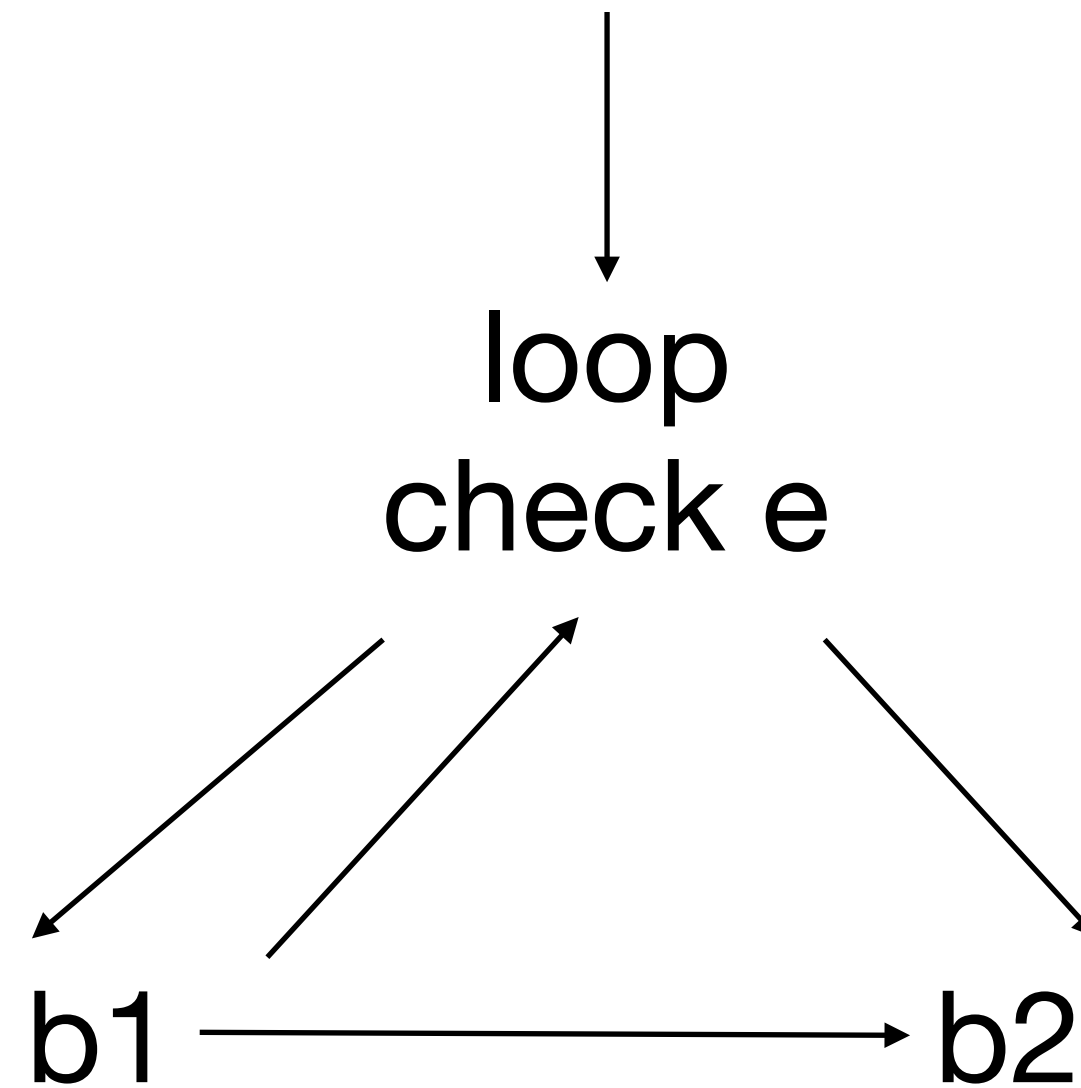
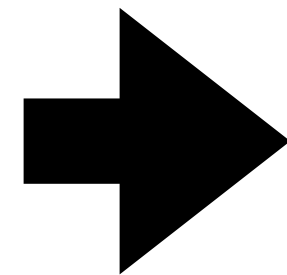
```
while e {  
  b1  
}  
b2
```



Notice: loop has 2 predecessors, so it is a join point, add block parameters

Imperative to SSA

```
while x != 0 {  
  x := x - 1  
  if y > 10 {  
    break  
  }  
  ...  
}  
b2
```

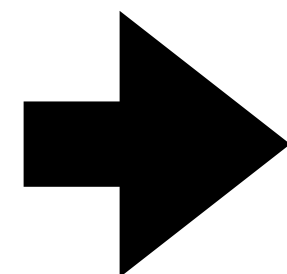


If we can break, then b1 can branch directly to b2

if break is used, b2 is **also** a join point

Imperative to SSA

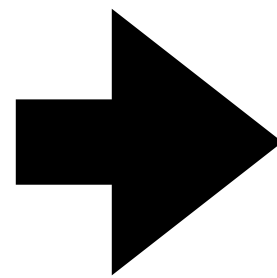
```
while e {  
    b1  
}  
b2
```



```
loop(...): ;; loop is a join point, include all in-scope vars  
done(...): ;; done is a join point as well because of break  
    ... ;; compiled code for b2  
body():  
    ... ;; compiled code for b1  
    br loop(...)  
...  
c = ... ;; compiled code for e  
cbr c body() done(...)  
br loop(...)
```

Imperative to SSA

```
var m = 100
var n = 25
while ! (m == n) {
  if m < n {
    n := n - m
  } else {
    m := m - n
  }
}
return m
```



```
m0 = 100
n0 = 25
loop(m2, n2):
  done(m1, n2):
    return m1
  body(m3, n3):
    lt():
      n4 = n3 - m3
      br loop(m3, n4)
    gt():
      m4 = m3 - n3
      br loop(m4, n3)
  b = m3 < n3
  cbr b lt() gt()
  c = m2 == n2
  d = not c
  cbr d body(m2, n2) done(m2, n2)
loop(m0, n0)
```

Minimal SSA

An SSA program is **minimal** if it uses as few block arguments (phi nodes) as possible.

Useful for optimization: branching to a block with arguments is compiled to a **mov**, potentially causing memory access. Want to reduce these as much as possible.

Minimal SSA Form

Translating Imperative code to SSA using crude phi node insertion produces **very** non-minimal SSA: many extra block parameters

But because imperative code is well-structured, block sinking is not necessary, blocks are already nested inside their immediate dominators

Only need to implement parameter dropping.

Theorem: crude **phi** node insertion + parameter dropping produces minimal SSA

Why all the trouble?

Modern compiler infrastructure for imperative languages:

input program: mutates variables directly, variables similar semantics to registers

middle end: translates into SSA, functional intermediate representation where variables are never mutated

backend: translate out of SSA, map variables to registers (or memory), mutate their values

SSA Benefits

Programs are **easier** to reason about

Common sub-expression elimination:

y and z have the same definition, so just replace z with y.

Valid with SSA

Not valid in imperative code

```
x = 1;  
y = x + 1;  
  
z = x + 1;
```

SSA Benefits

Programs are **easier** to reason about

Common sub-expression elimination:

y and z have the same definition, so just replace z with y.

Valid with SSA

Not valid in imperative code

```
x = 1;  
y = x + 1;  
x = 2;  
z = x + 1;
```

SSA Benefits

Program analyses can be implemented more **efficiently**.

Can set up data structures that map variable uses directly to their definitions. Skips over a great deal of irrelevant information.

In an imperative program variables can be updated anywhere, putting the program in SSA form makes the dataflow information easier to access

```
x1 = 1;  
y = x1 + 1;  
x2 = 2;  
z = x2 + 1;
```

SSA Benefits

When program analysis is **easier**:

1. More efficient generated code: Easier for compiler writers to implement more and better analyses/optimizations
2. More efficient compiler: accessibility of information in SSA form allows efficient data structures for program analysis, since more information is manifest in the program format

SSA History, Benefits

Further Reading: SSA Book Chapter 1